

Machine Learning Systems Design

Modeling Pipeline

Lecture 15: High-performance Modeling



CE 40959 Spring 2023

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[SharifMLSD.github.io](https://github.com/SharifMLSD)

Ways a model can scale

1. In complexity: architecture, number of parameters

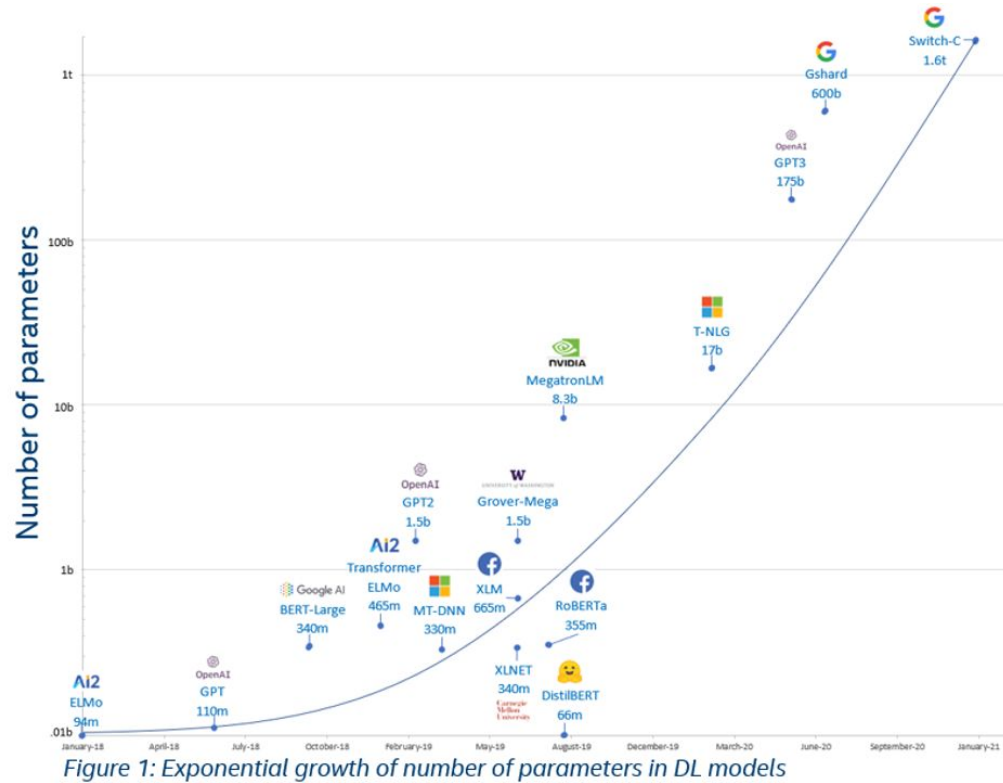
Ways a model can scale

1. In complexity: architecture, number of parameters
2. In prediction traffic

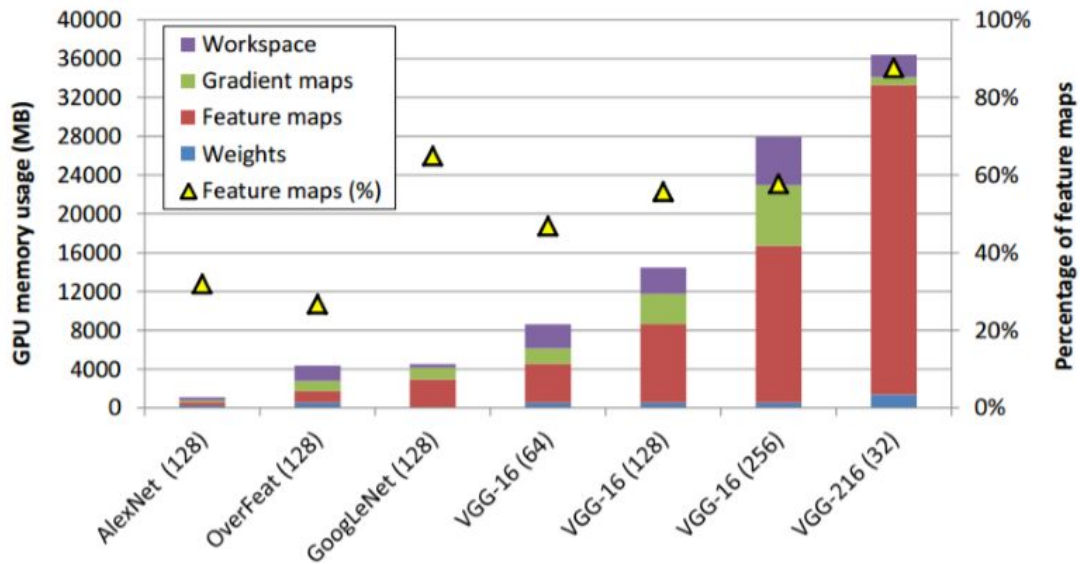
Ways a model can scale

1. In complexity: architecture, number of parameters
2. In prediction traffic
3. In number of models

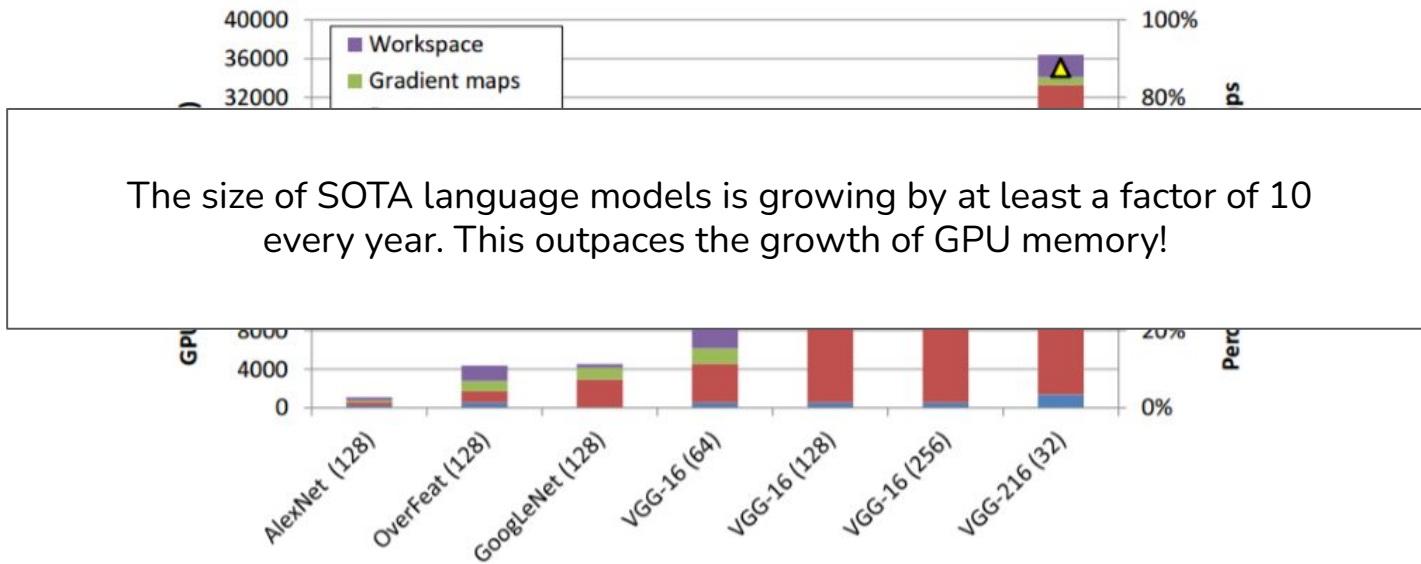
Rise of Incredibly Large DL Models



GPU Usage



GPU Usage

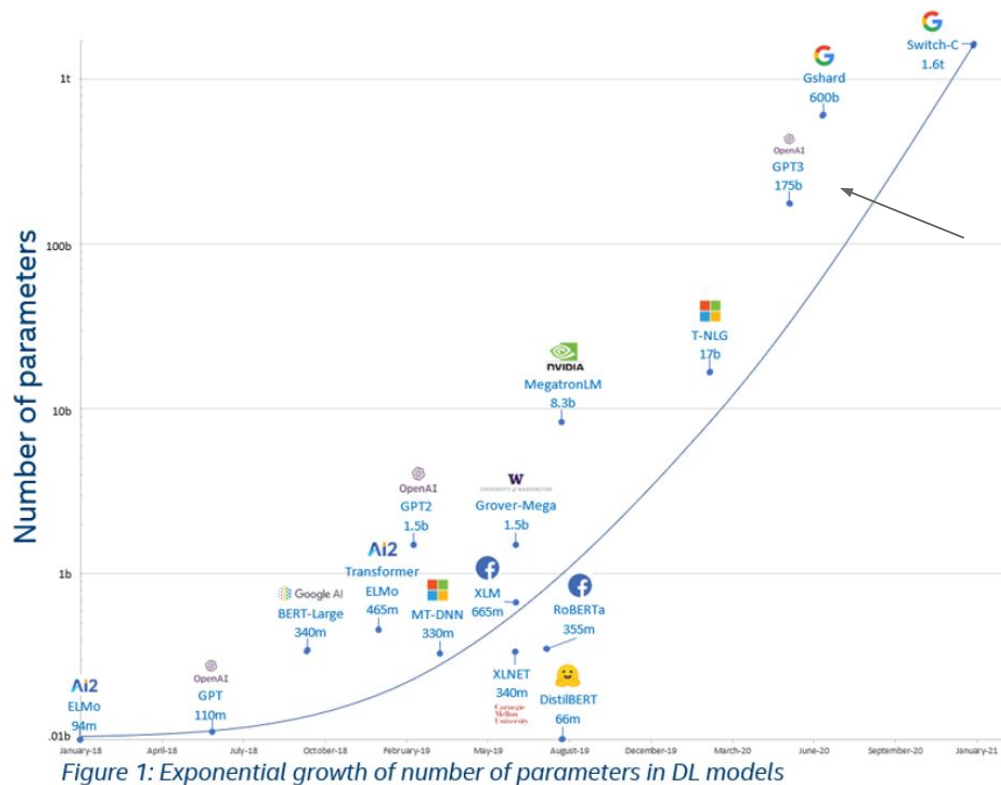


Issues

- A smaller batch size can lead to
 - More iterations necessary to converge
 - Decreased stability

-> What about when the model itself doesn't fit into GPU memory? Or when even a single data sample doesn't fit into GPU memory?

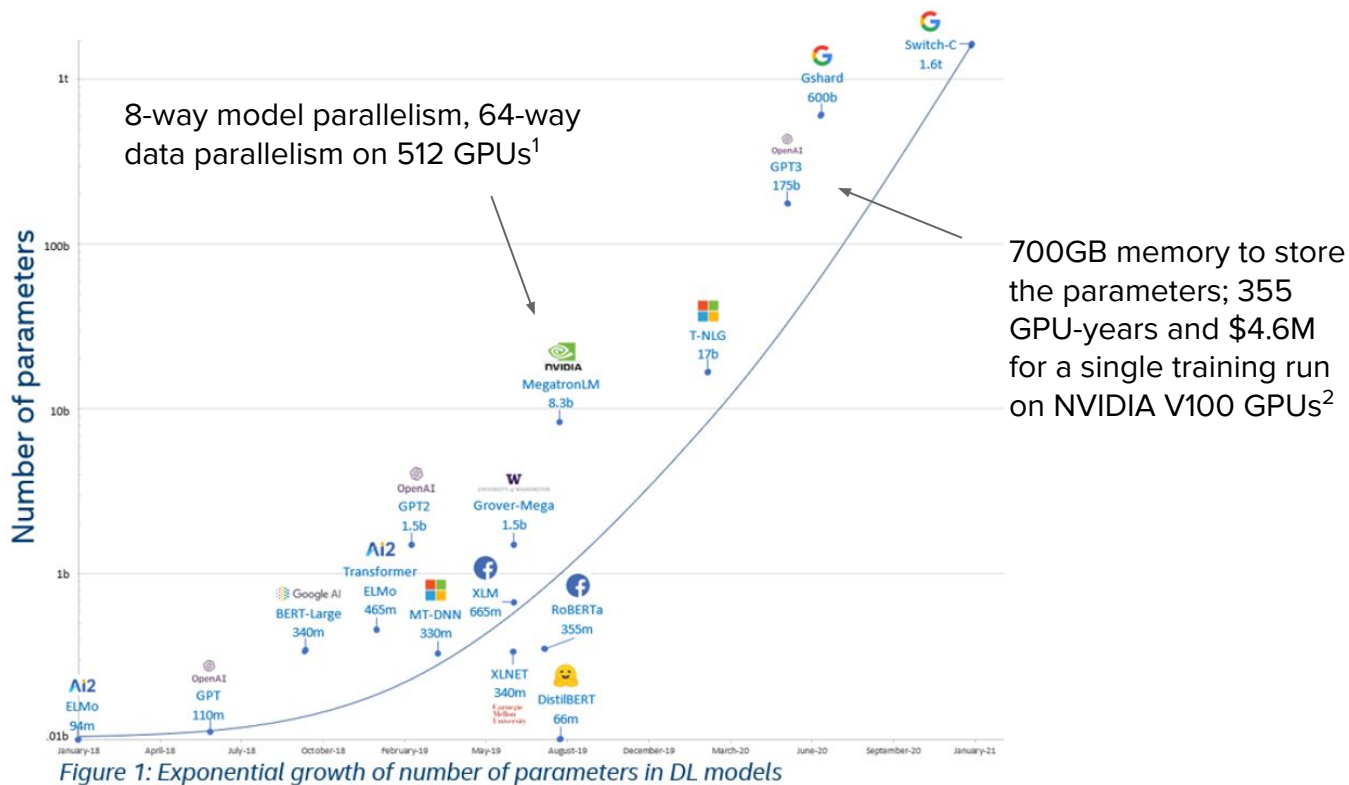
Distributed Training



700GB memory to store the parameters; 355 GPU-years and \$4.6M for a single training run on NVIDIA V100 GPUs²

Figure 1: Exponential growth of number of parameters in DL models

Distributed Training



Distributed Training

Data parallelism

Model parallelism

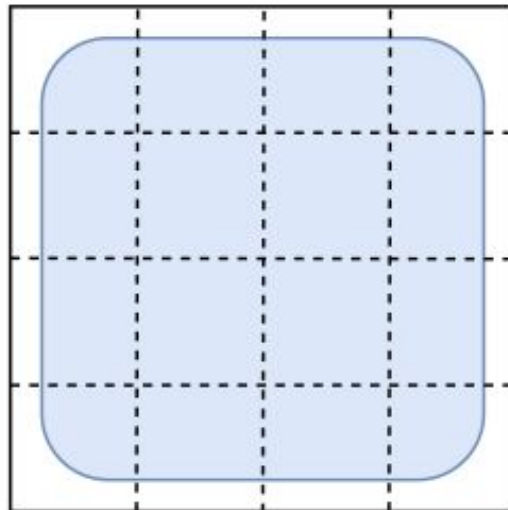
Data Parallelism for Large Batch Training

Split the data across devices

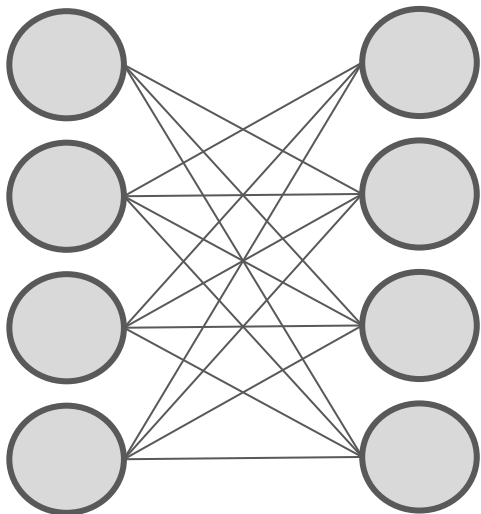
Each device sees a fraction of the batch

Each device replicates the model

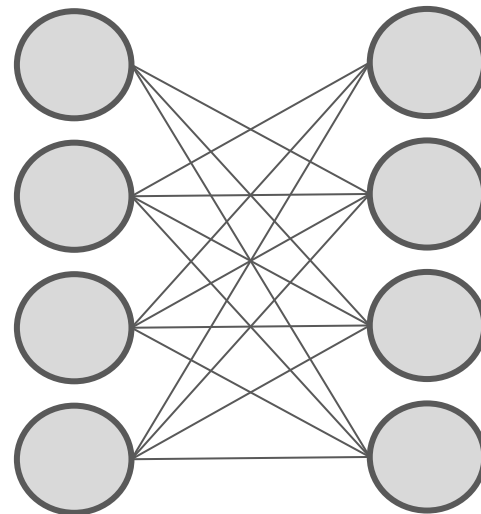
Each device replicates the optimizer



Replicate model across devices



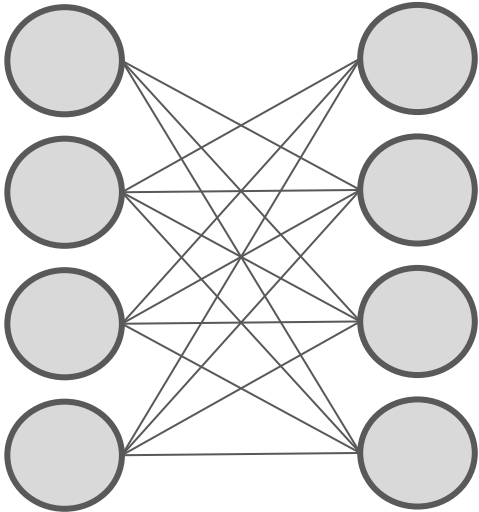
GPU 1



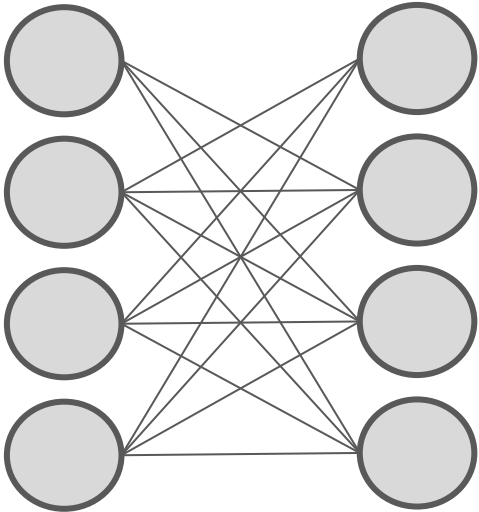
GPU 2

GPUs could be on same or multiple nodes

To push in a batch of data



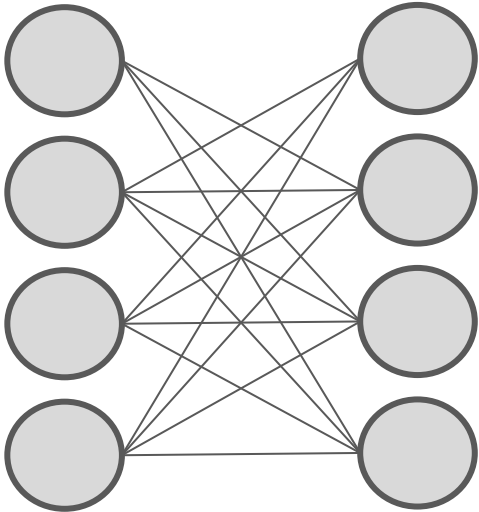
GPU 1



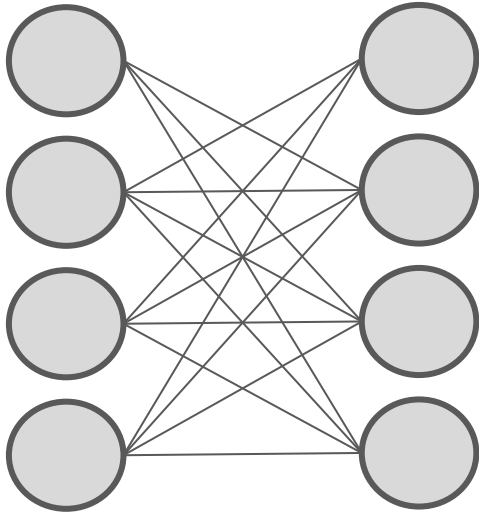
GPU 2



Split batch across devices



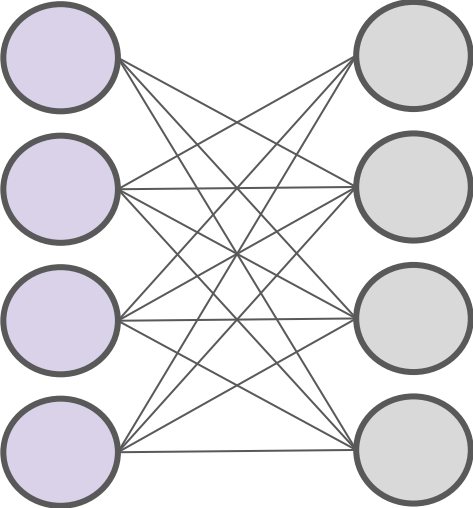
GPU 1



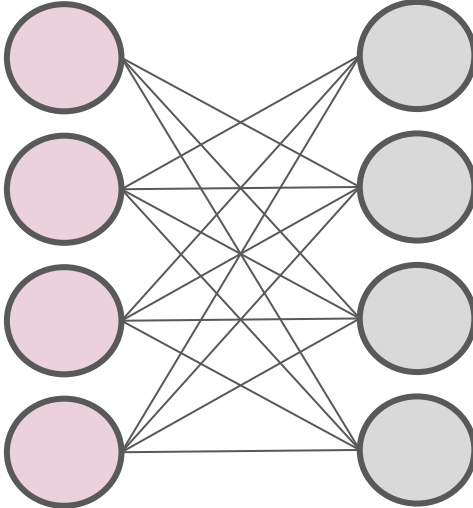
GPU 2



Parallel forward passes



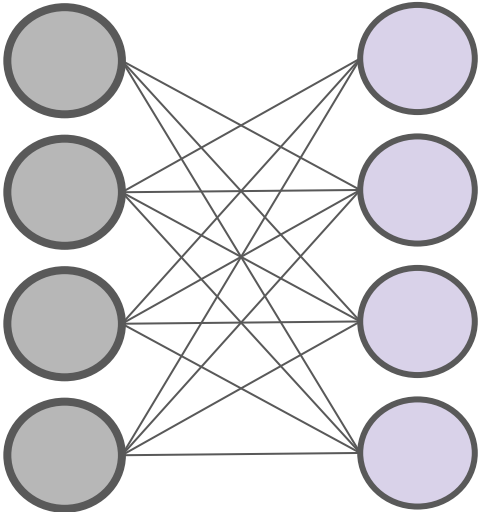
GPU 1



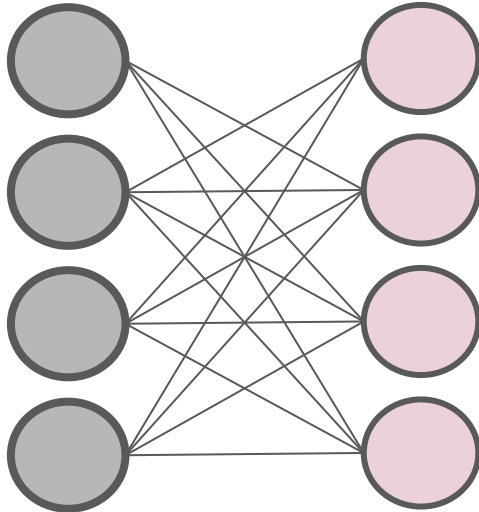
GPU 2



Parallel forward passes

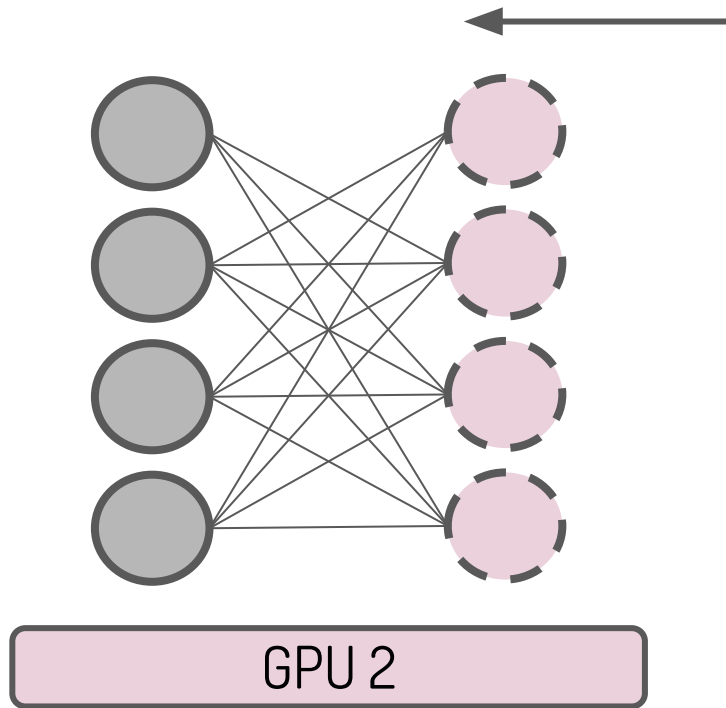
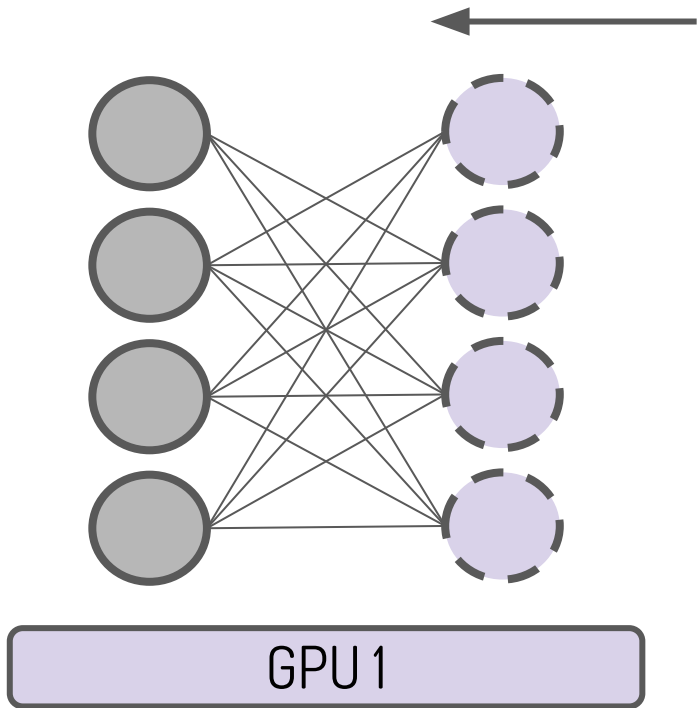


GPU 1

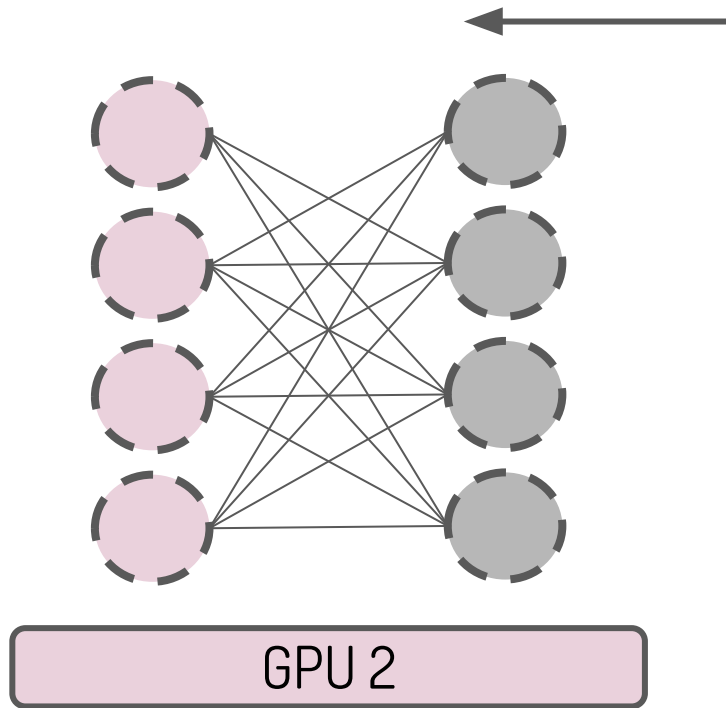
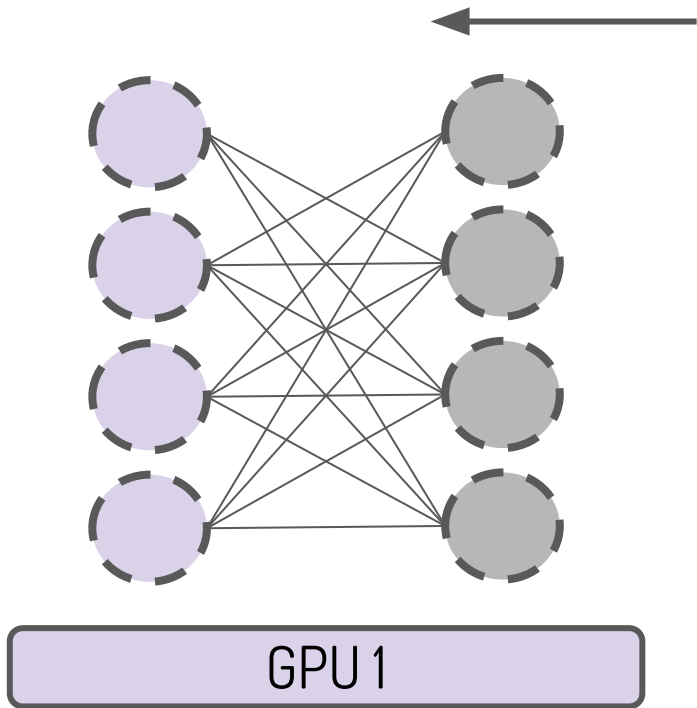


GPU 2

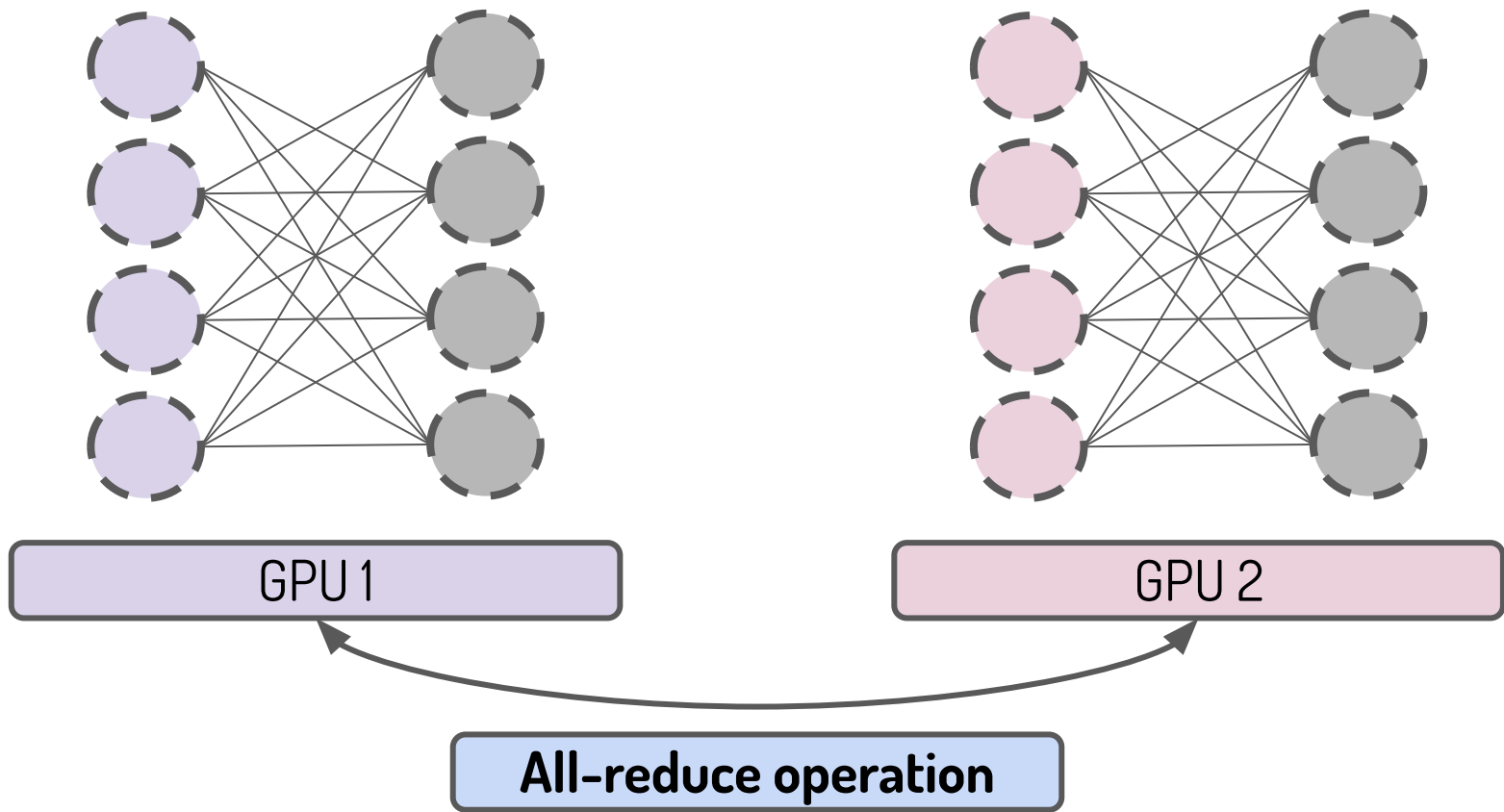


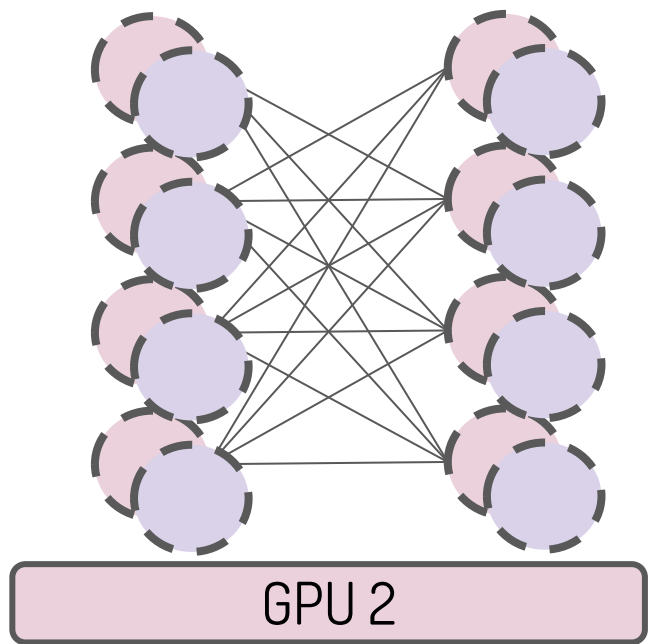
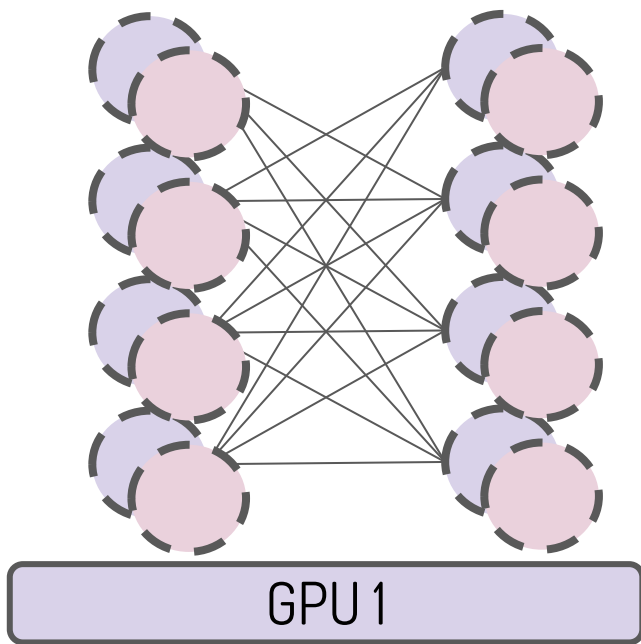


Backpropagate gradients

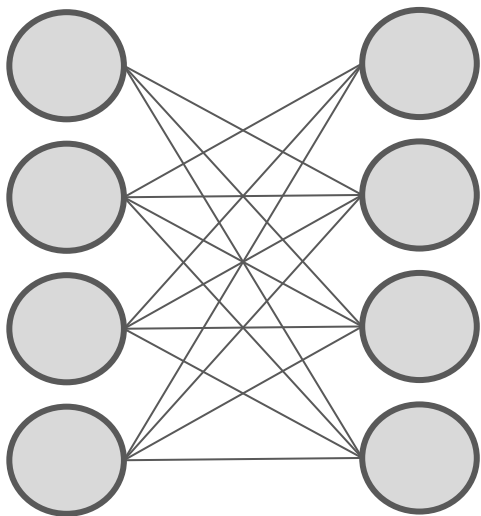


Backpropagate gradients

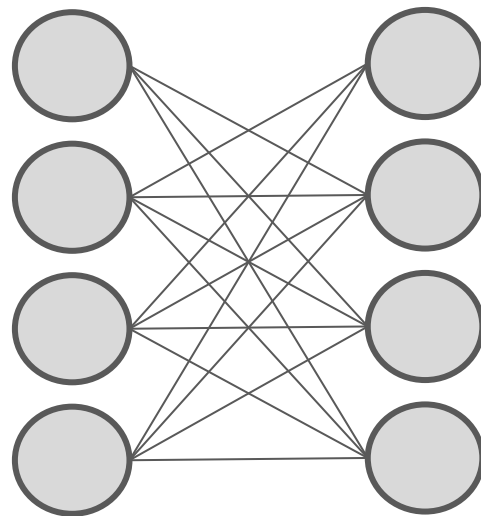




All devices do the same gradient updates



GPU 1



GPU 2

All parameters stay synchronized!

Data Parallelism

Split the data across devices

Each device sees a fraction of the batch

Each device replicates the model

Each device replicates the optimizer

GPT-3: 3.2M batch size

1M samples

- 1000 samples/batch/machine
- 1 machine: 1000 batches
- 100 machines: **10 batches**

Data Parallelism

Split the data across devices

Each device sees a fraction of the batch

Each device replicates the model

Each device replicates the optimizer

GPT-3: 3.2M batch size

Challenge 1: Learning rate

- Too small -> too long to converge
- Too large -> unstable learning

Data Parallelism: LR Scaling

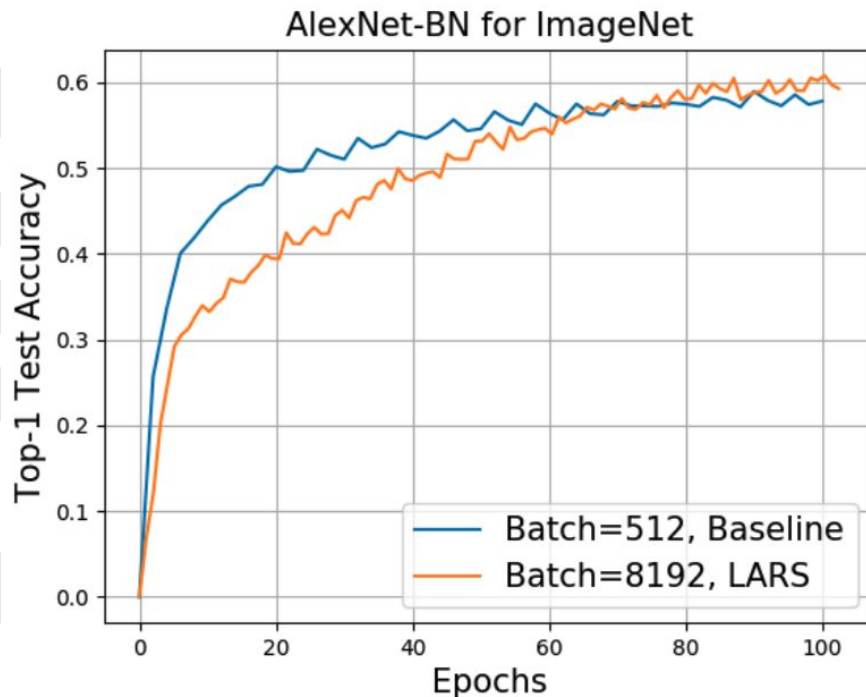
Split the data across devices

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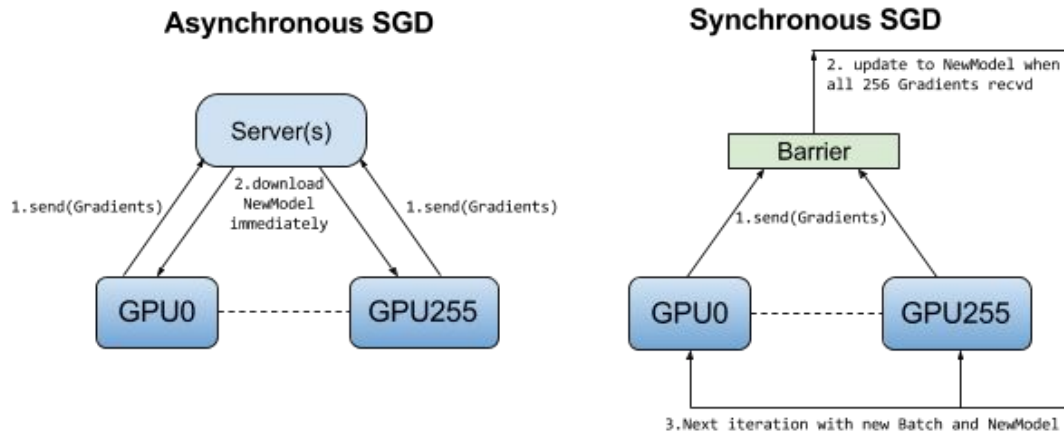
GPT-3: 3.2M batch size



Data Parallelism: Gradient Updates

Challenge 2: How to aggregate gradient updates?

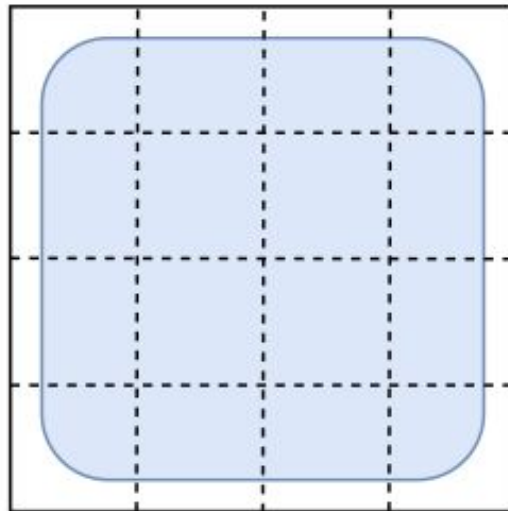
- Synchronous: have to wait for stragglers
- Asynch: gradients become stale



Solution: Model Parallelism for Large Model Training

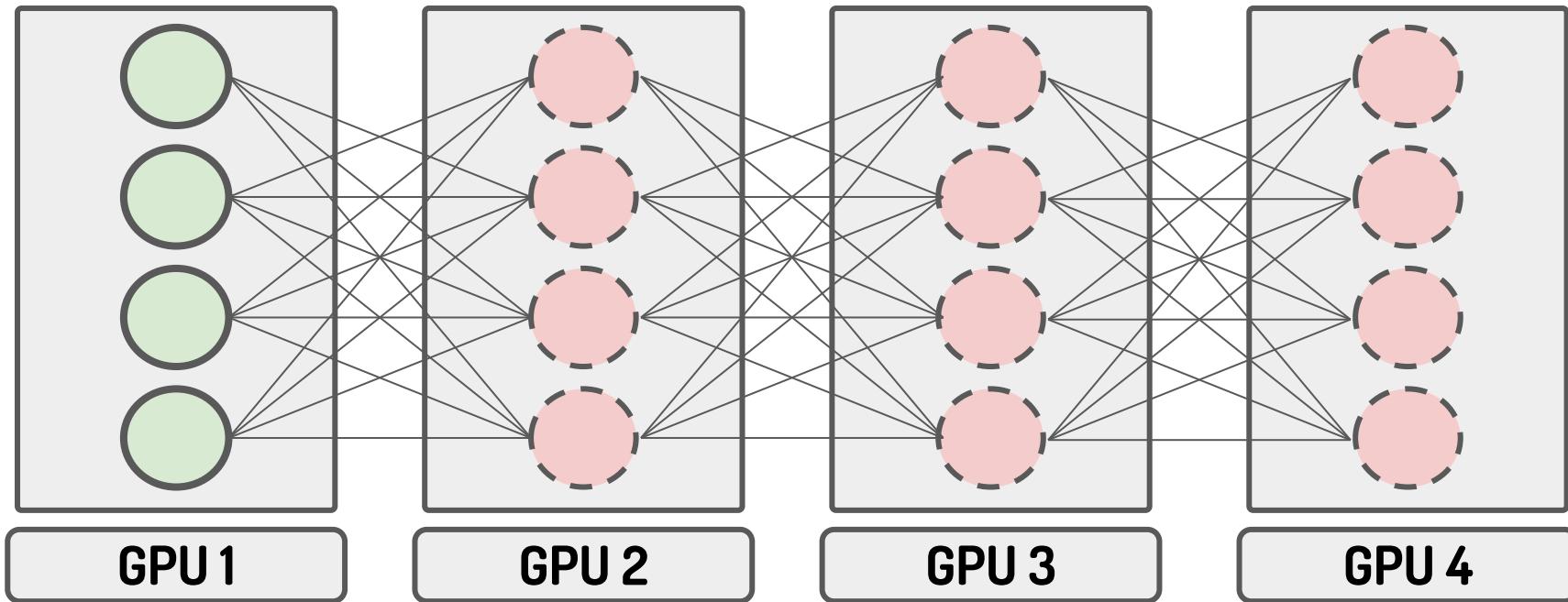
Split the model across devices

Each device runs a fragment of the model

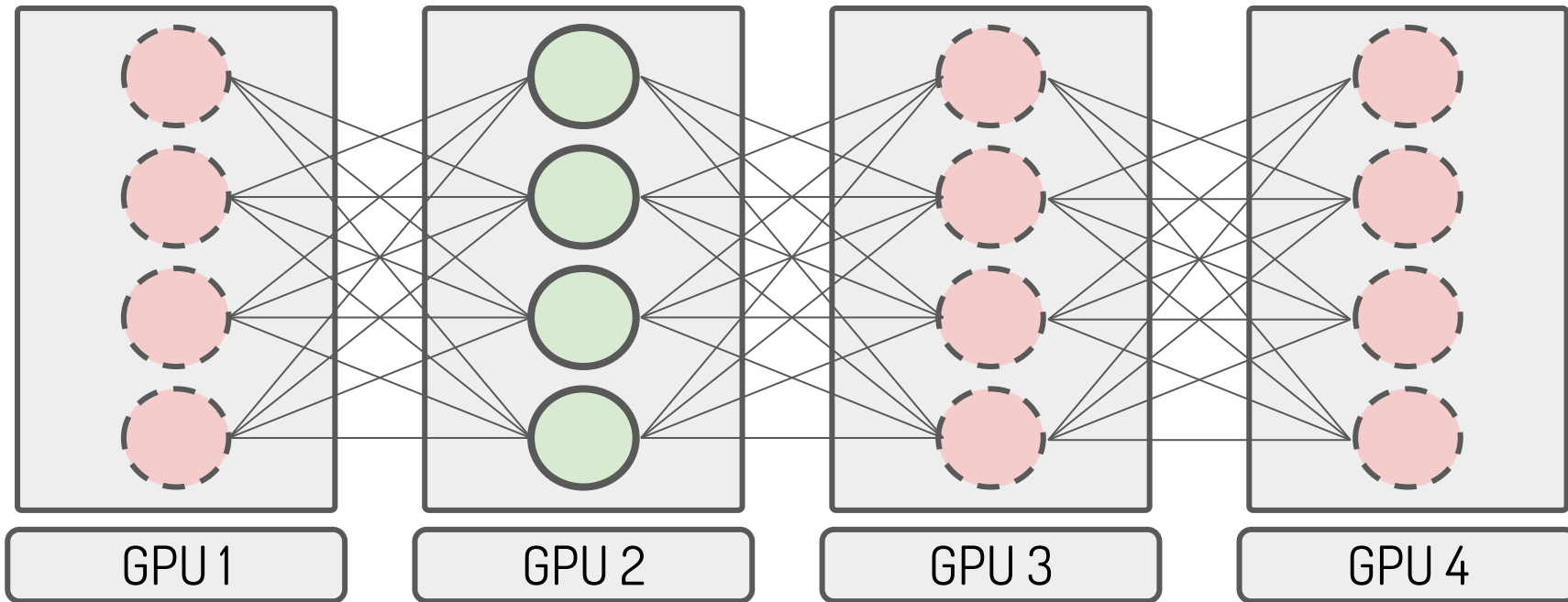


Model Parallelism: Naive

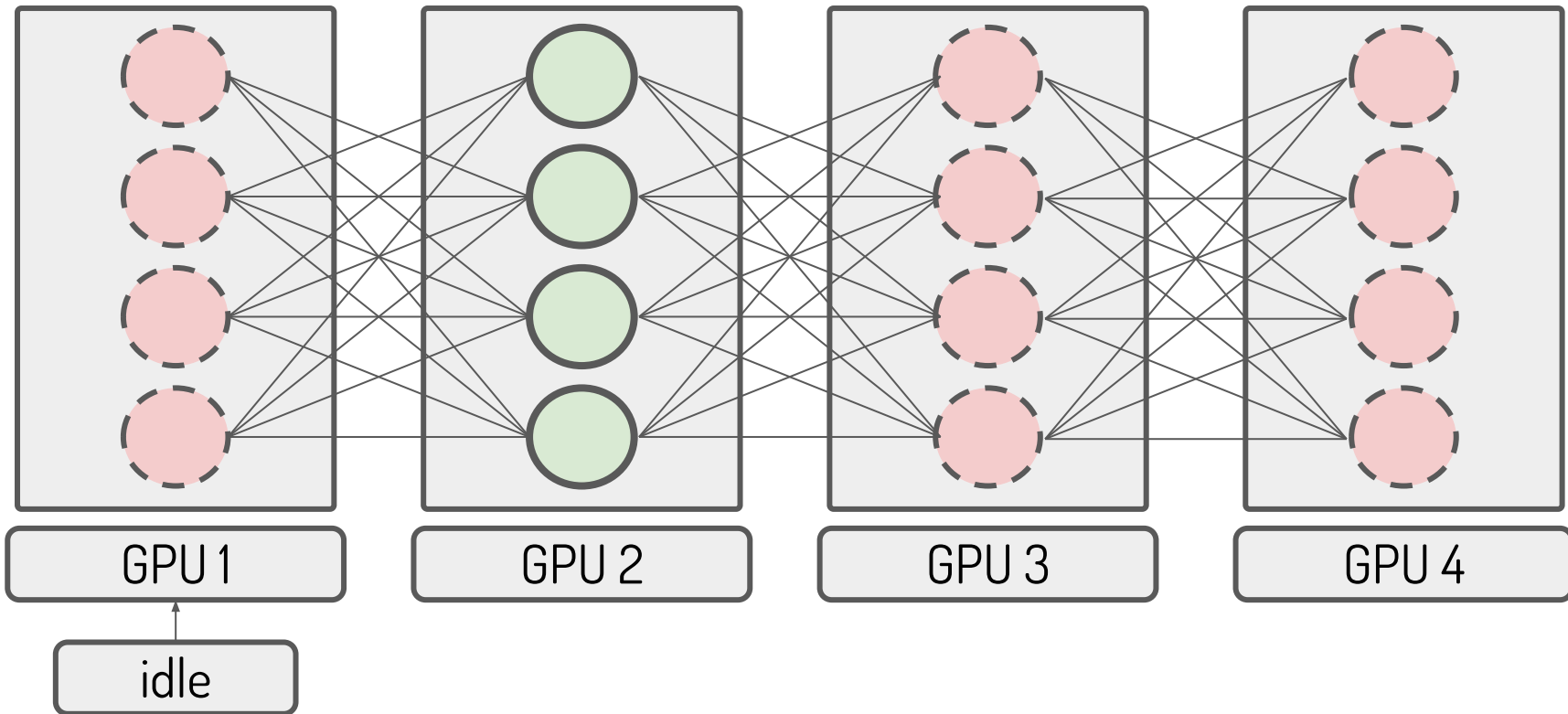
Model Parallelism: Naive



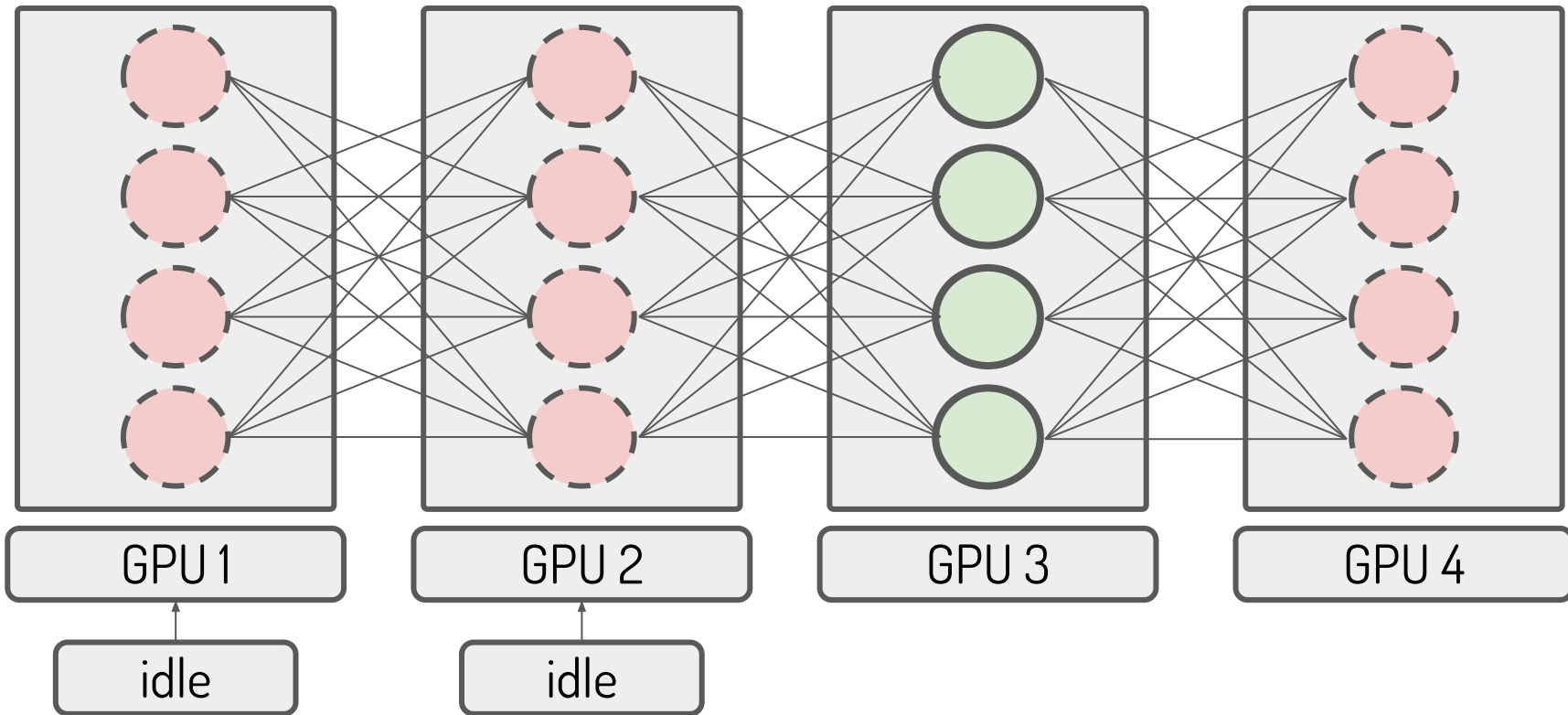
Model Parallelism: Naive



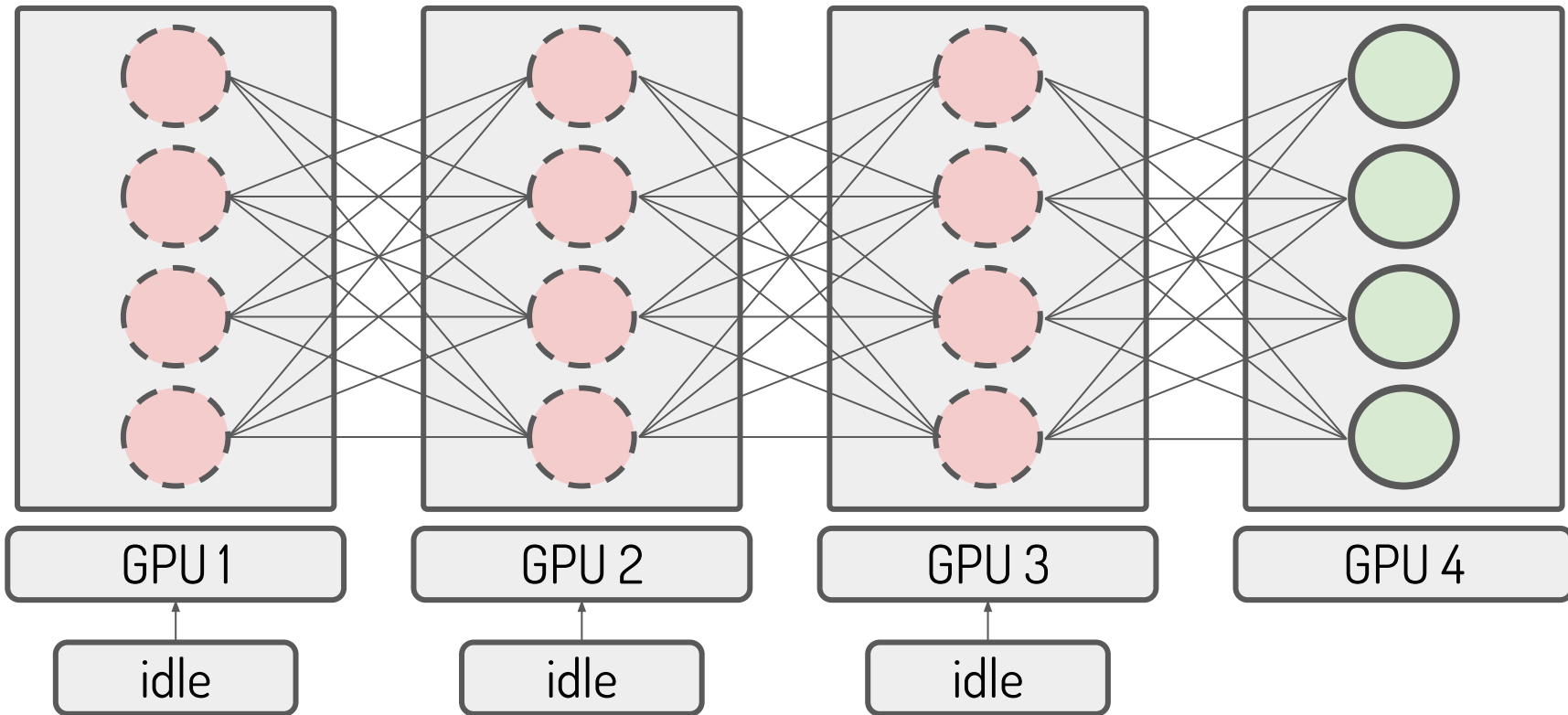
Model Parallelism: Naive



Model Parallelism: Naive

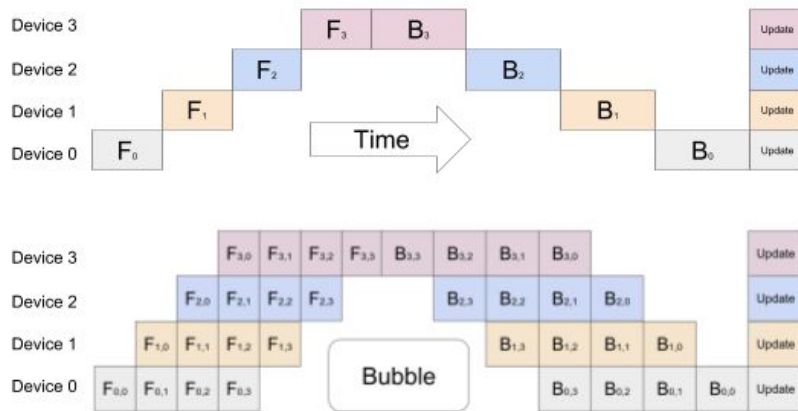


Model Parallelism: Naive



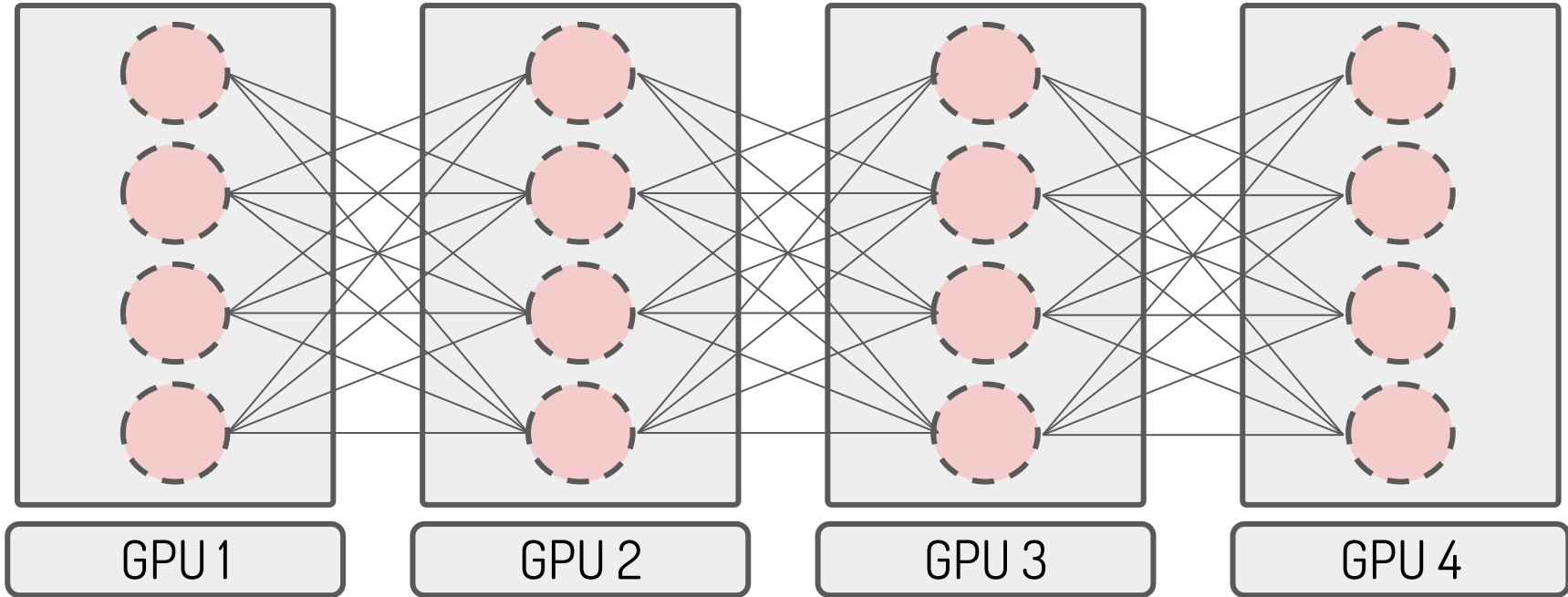
Pipeline Parallelism

Pipeline Parallelism



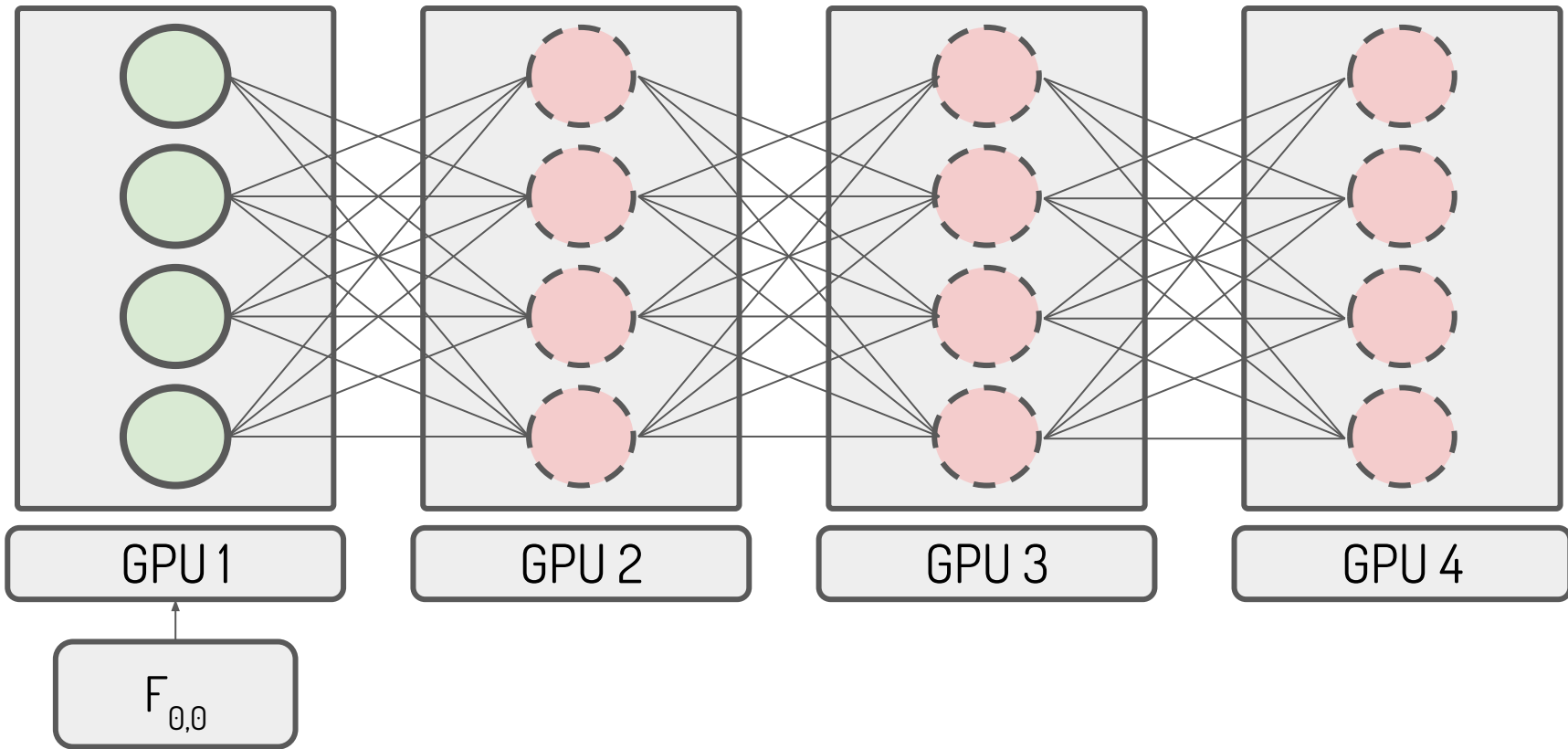
Top: The naive model parallelism strategy leads to severe underutilization due to the sequential nature of the network. Only one accelerator is active at a time. Bottom: GPipe divides the input mini-batch into smaller micro-batches, enabling different accelerators to work on separate micro-batches at the same time.

Pipeline Parallelism

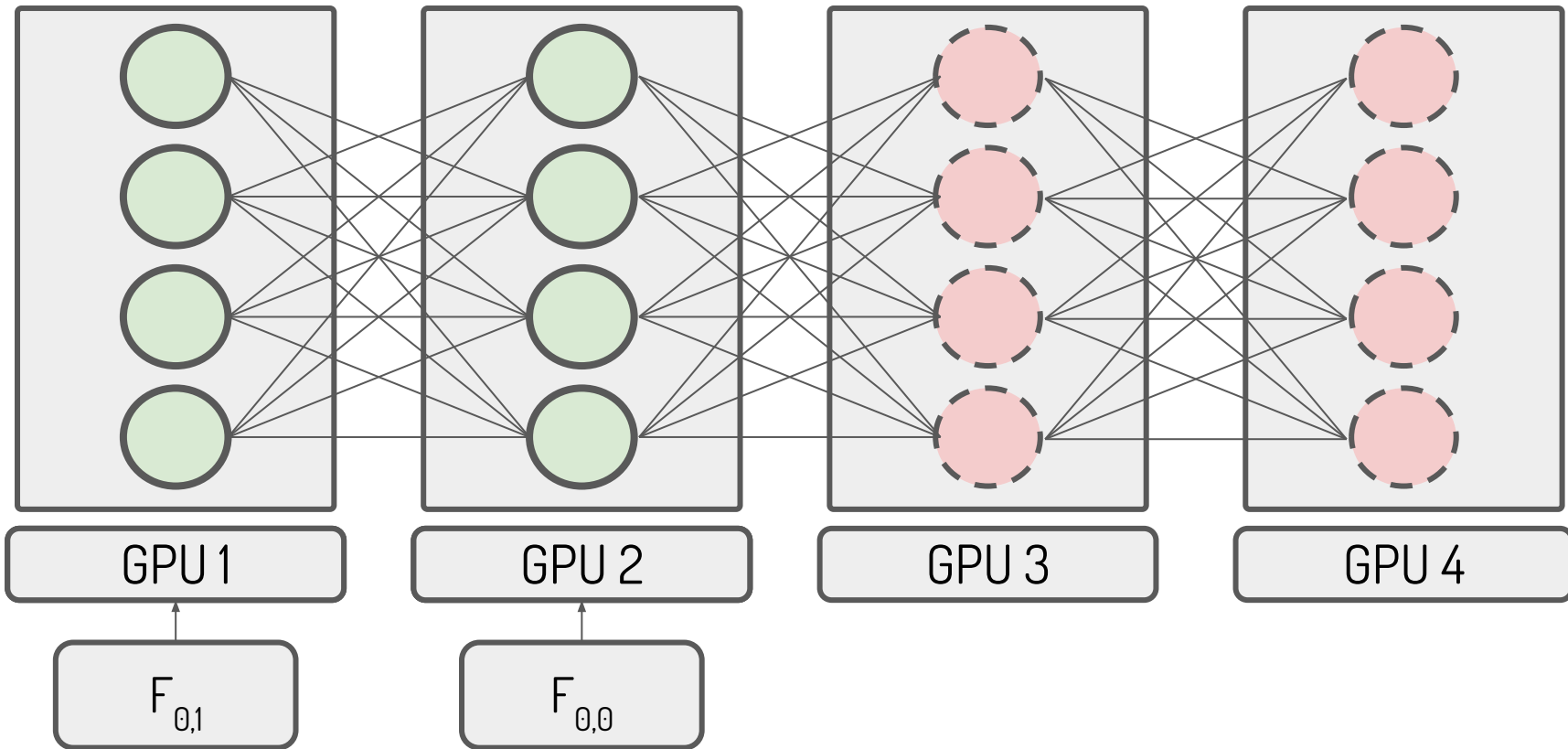


Split mini-batch into sequential micro-batches

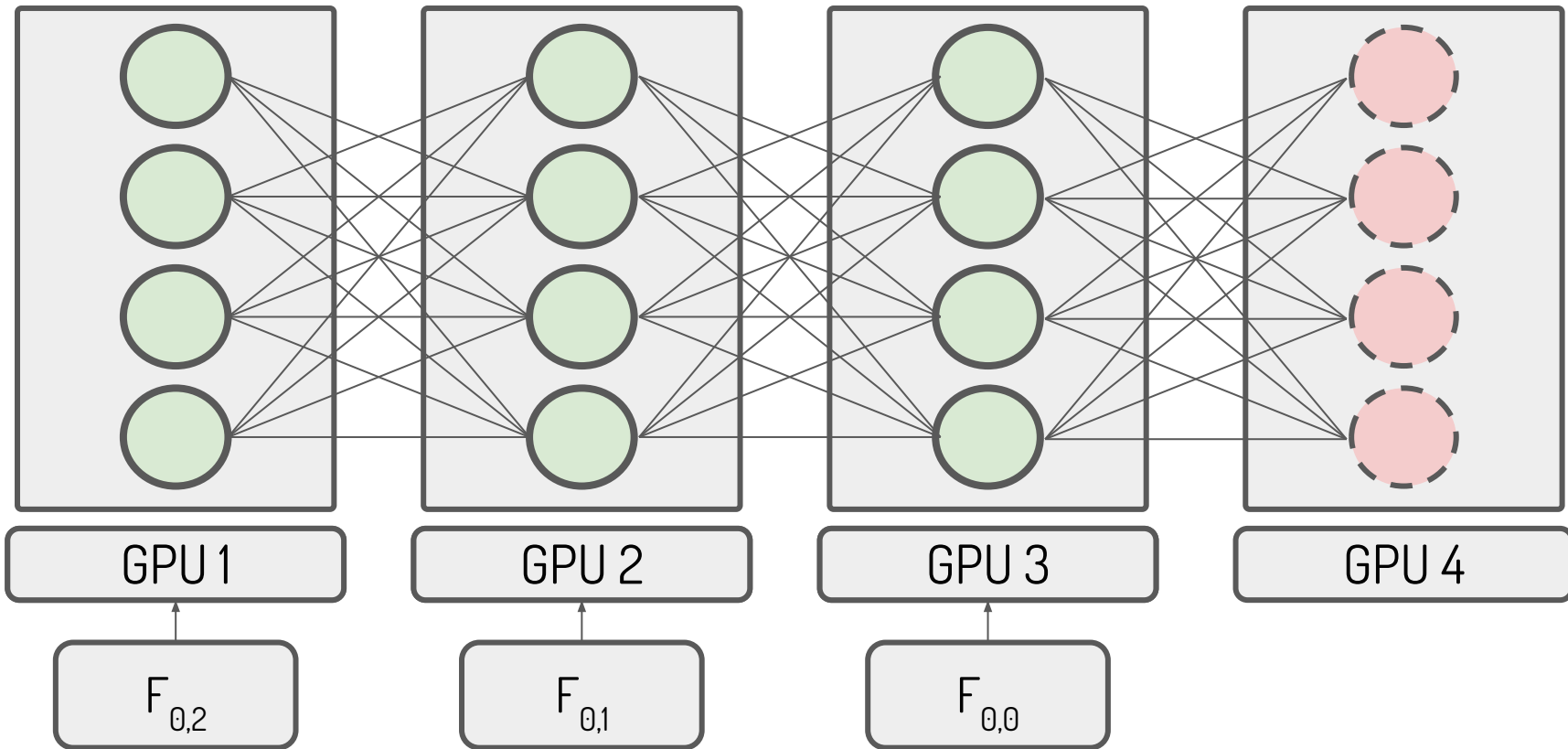
Pipeline Parallelism



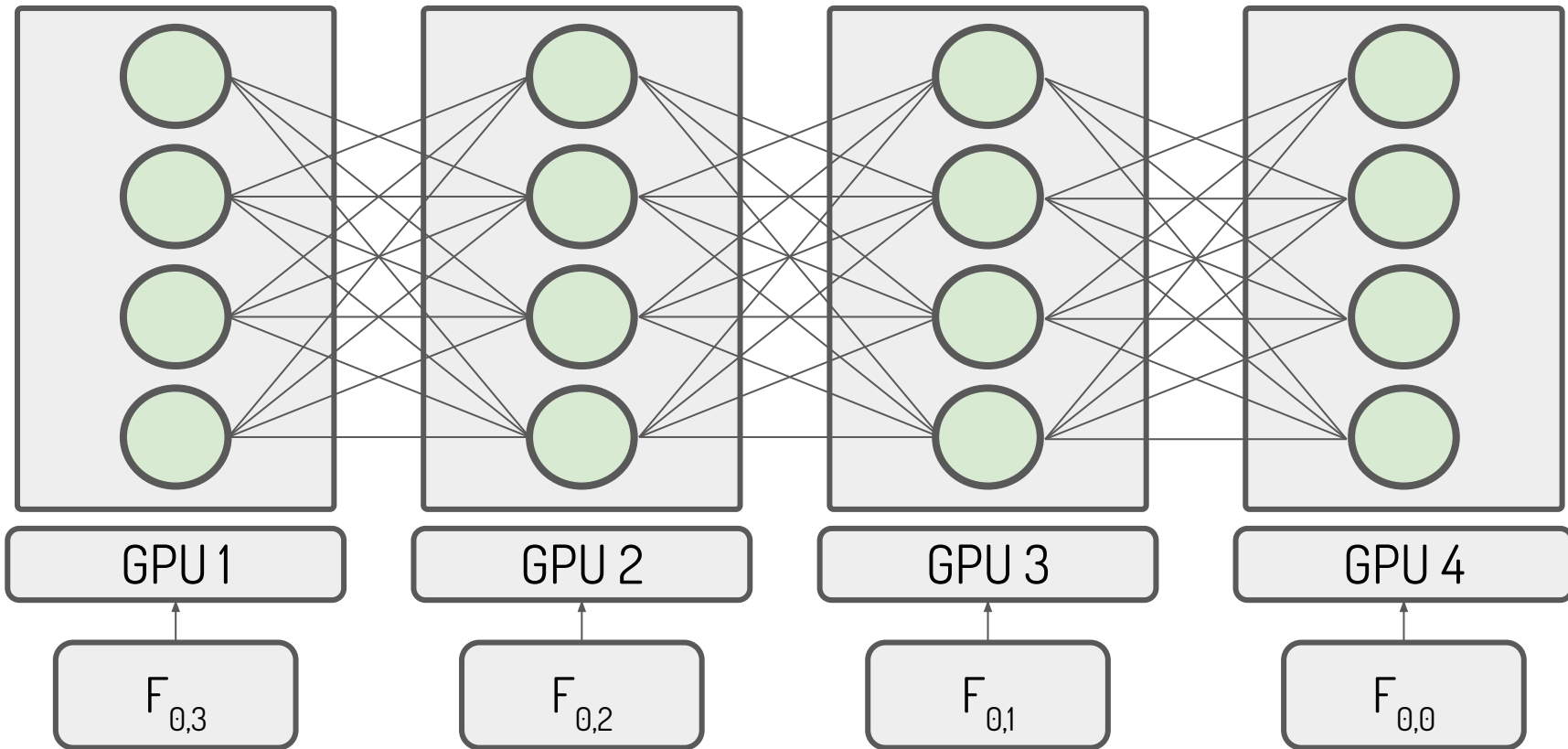
Pipeline Parallelism



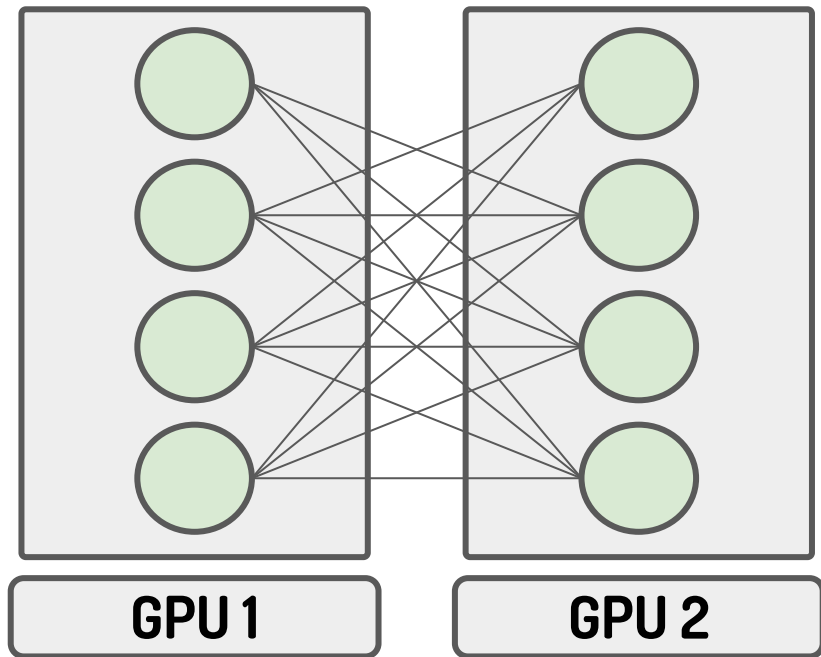
Pipeline Parallelism



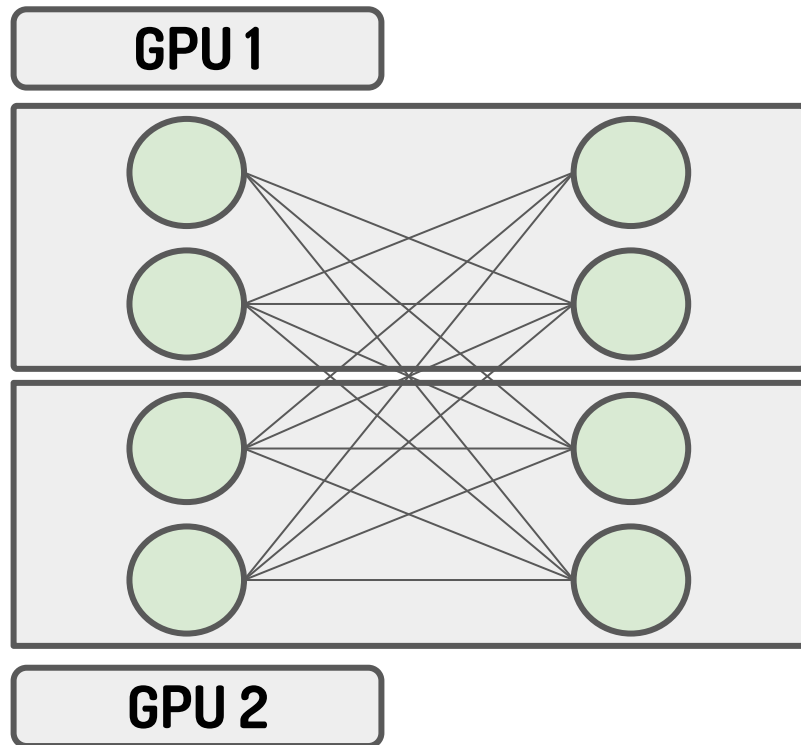
Pipeline Parallelism



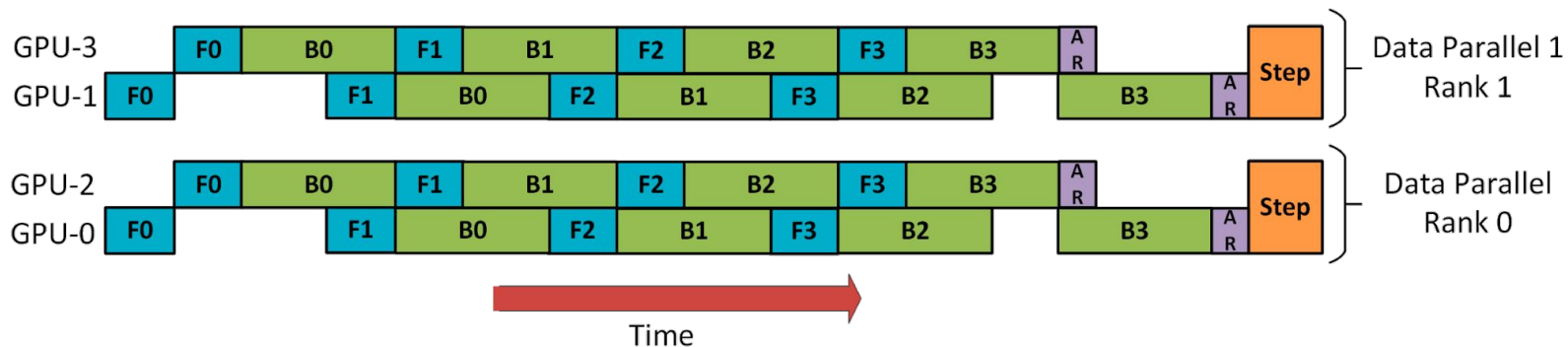
Pipeline Parallelism



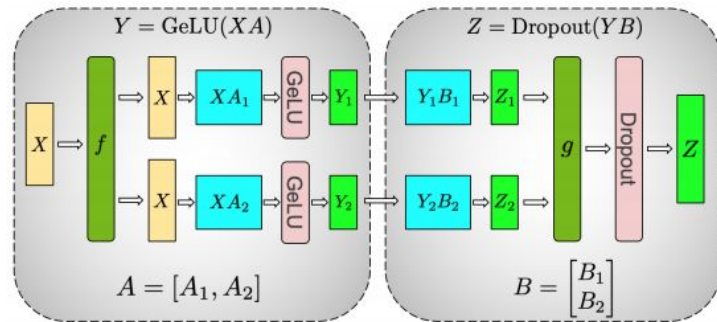
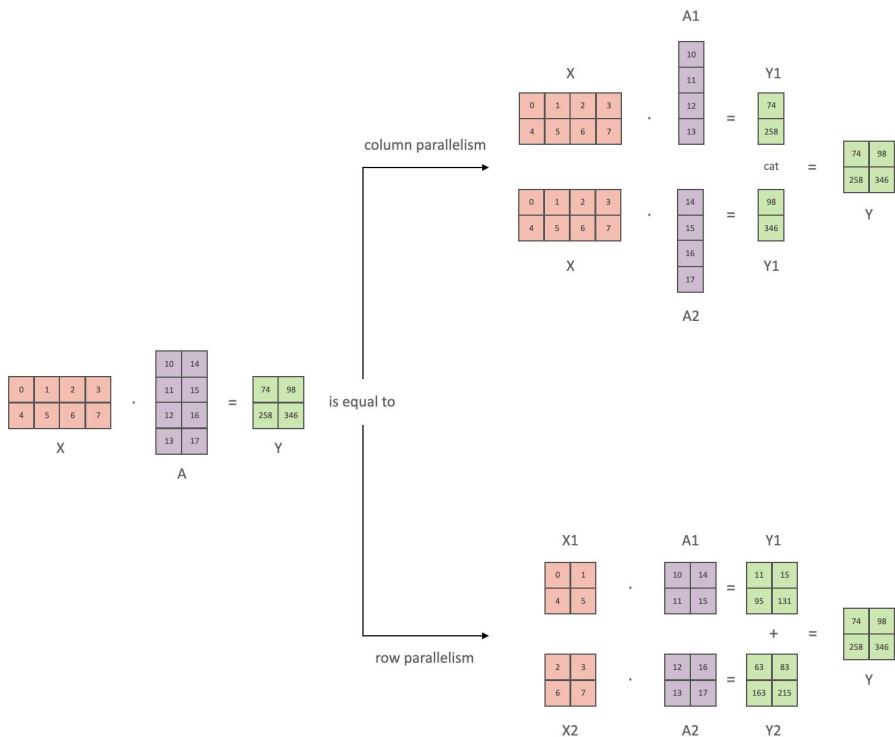
Distributed Tensor Computation



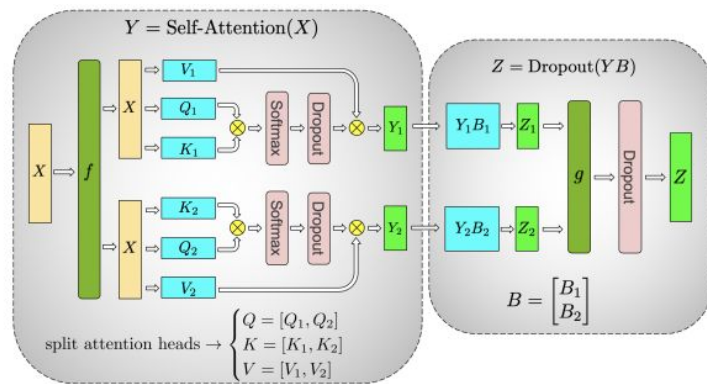
Combining Ideas!



Tensor Parallelism



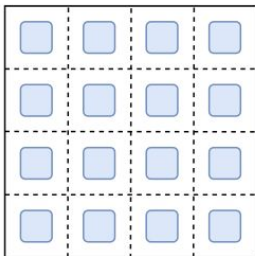
(a) MLP



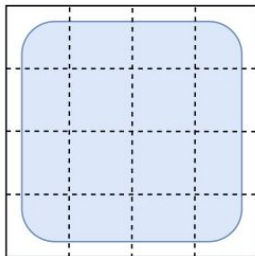
(b) Self-Attention

How the *model weights* are split over cores

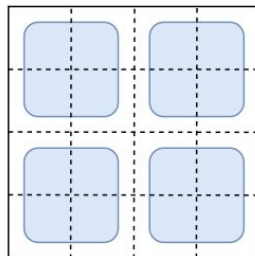
Data Parallelism



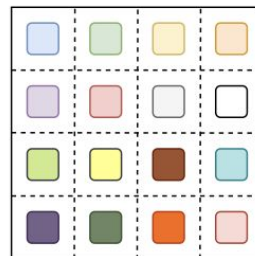
Model Parallelism



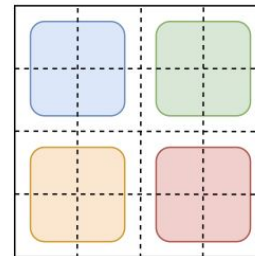
Model and Data Parallelism



Expert and Data Parallelism

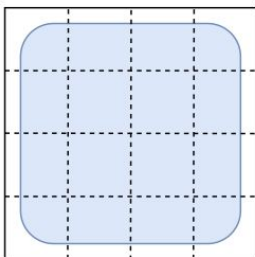


Expert, Model and Data Parallelism

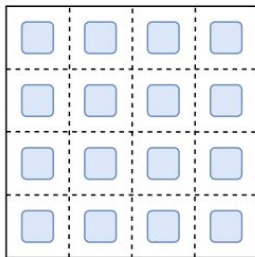


How the *data* is split over cores

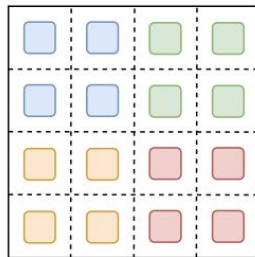
Data Parallelism



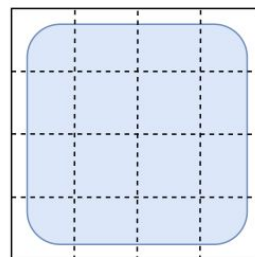
Model Parallelism



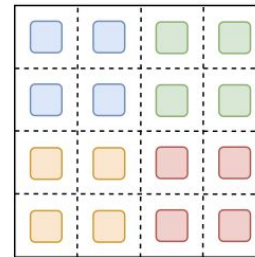
Model and Data Parallelism



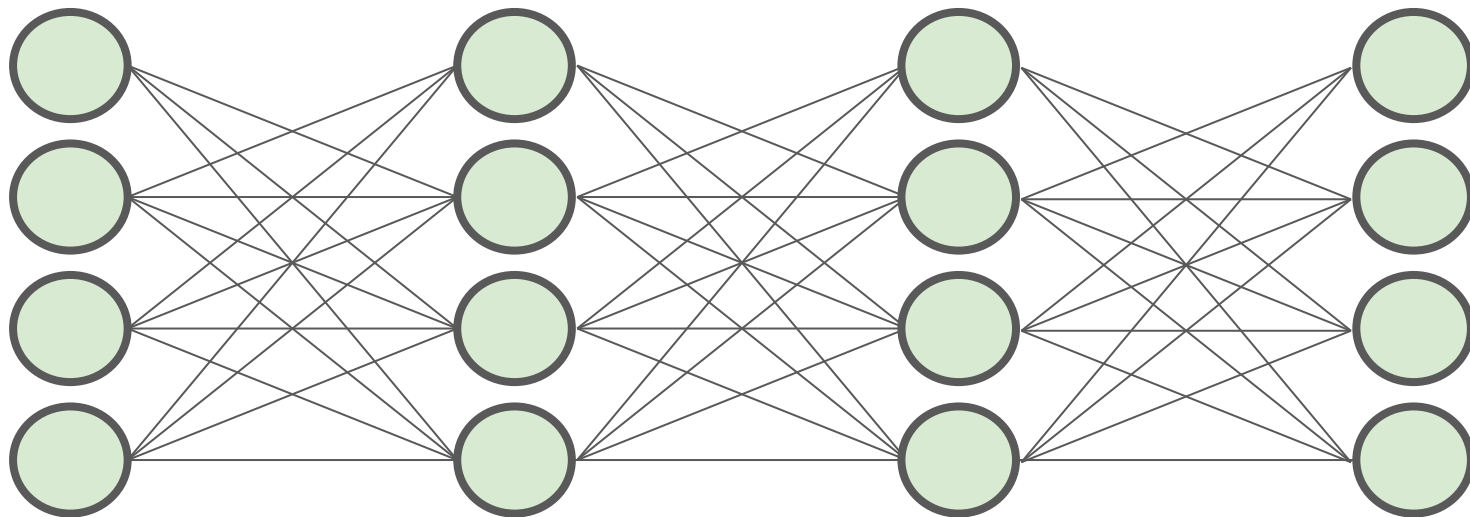
Expert and Data Parallelism



Expert, Model and Data Parallelism



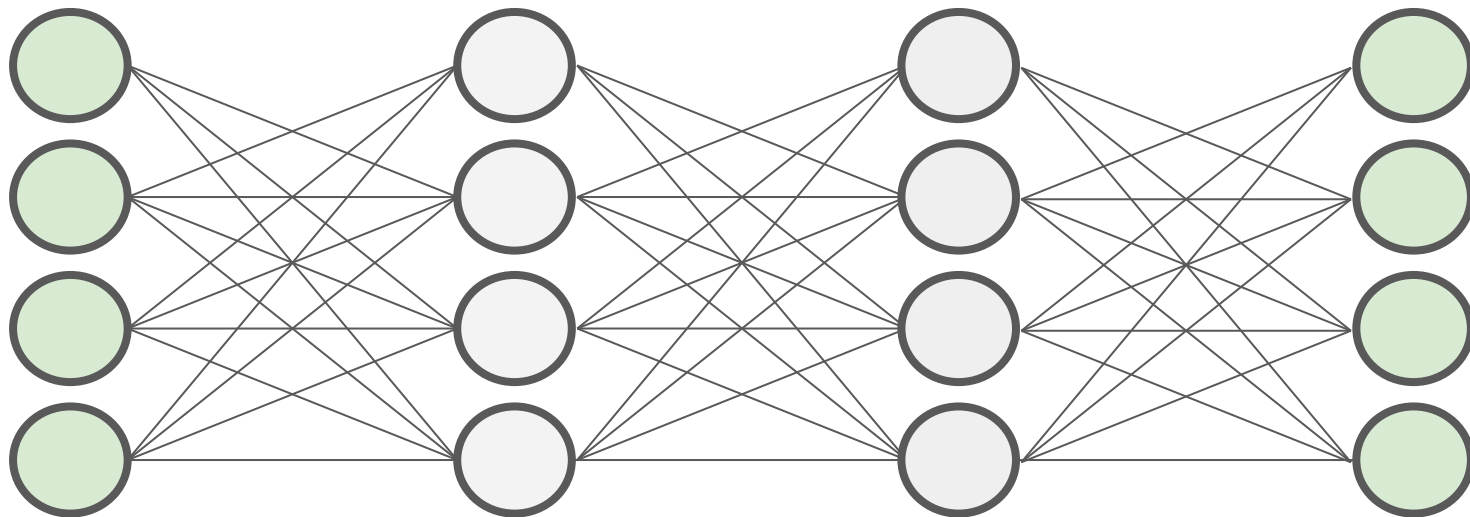
Gradient Checkpointing



GPU 1

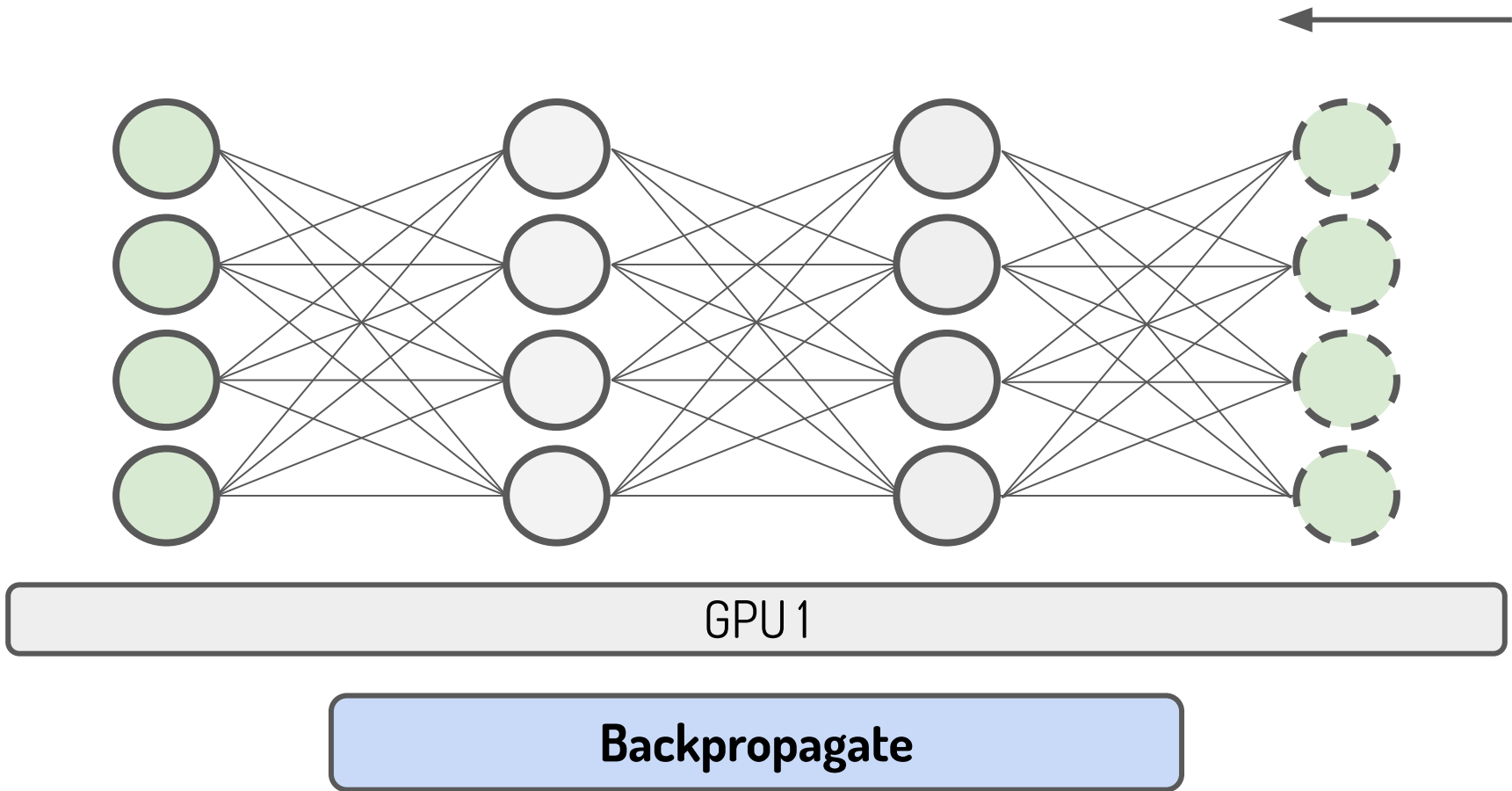
Trade off memory for compute

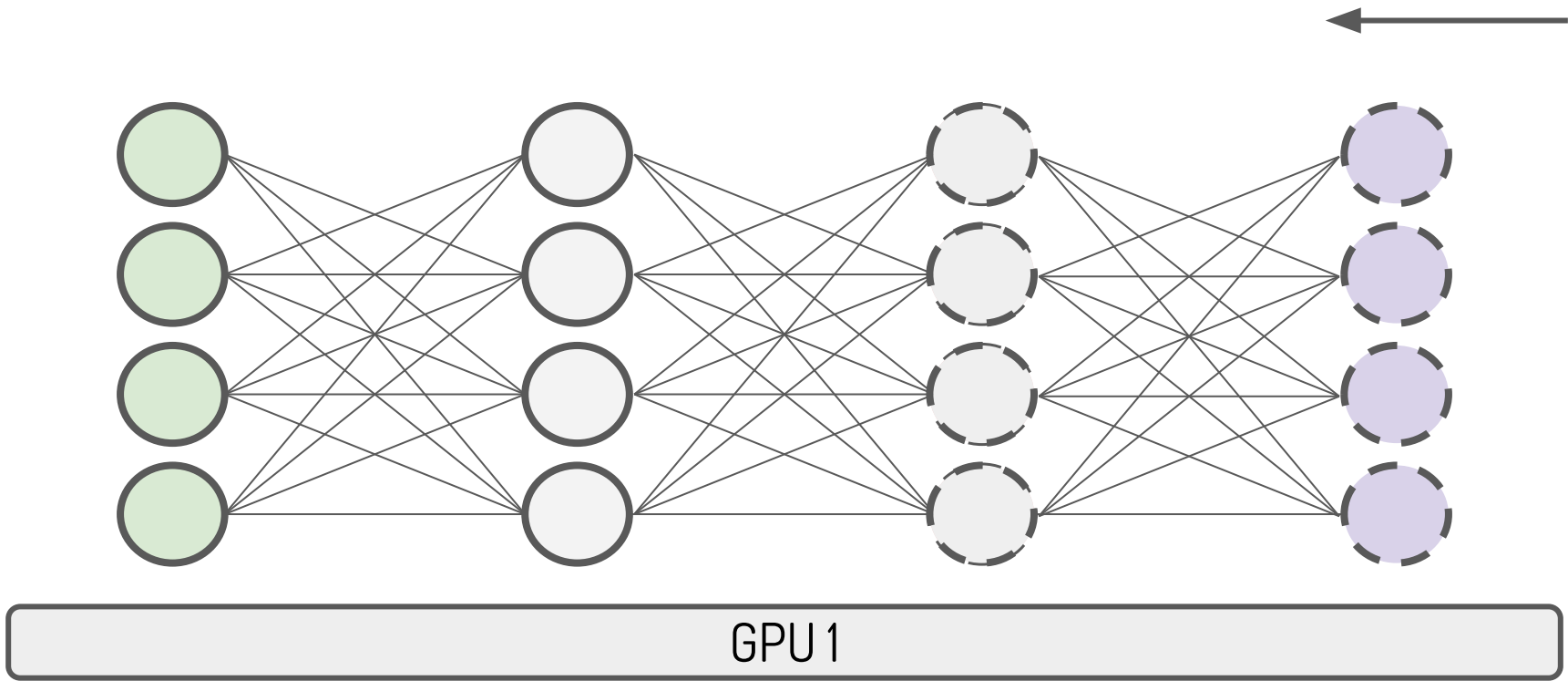
Gradient Checkpointing



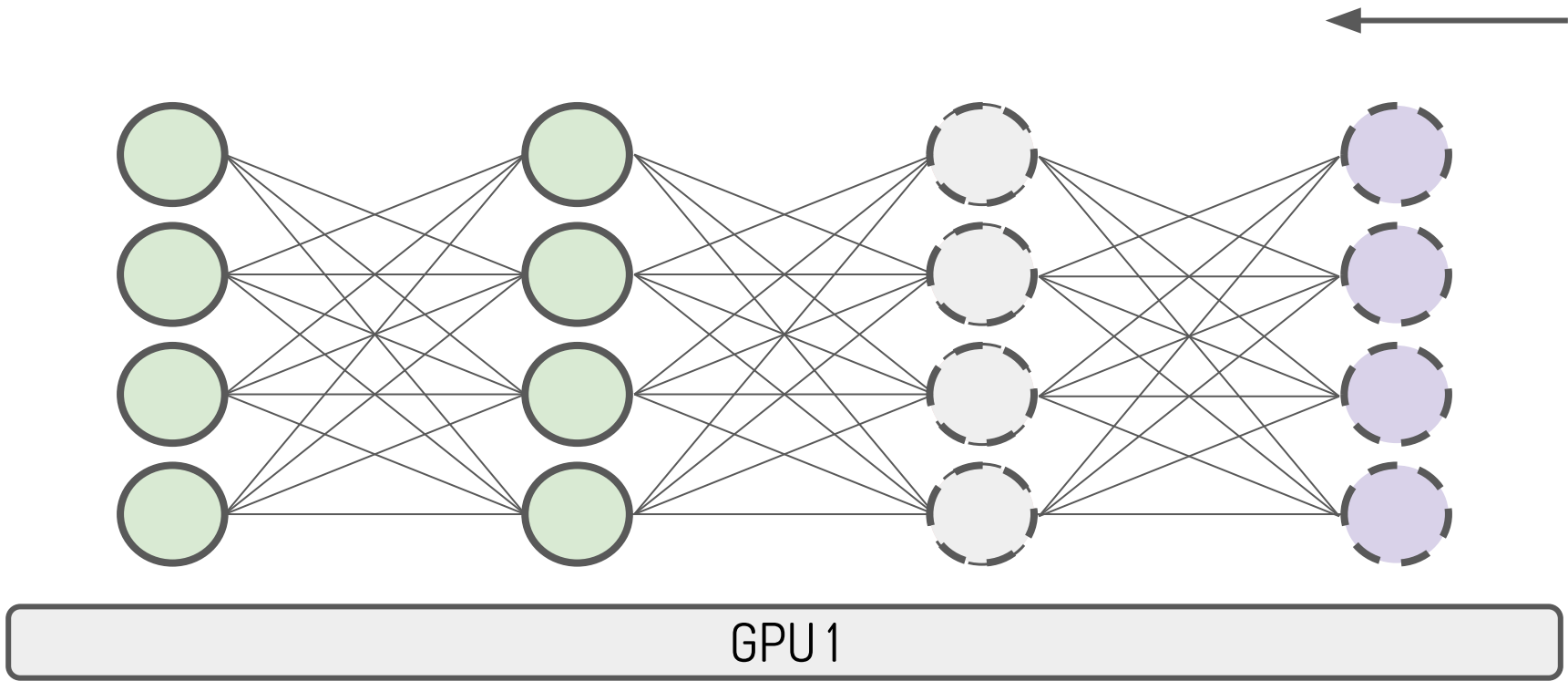
GPU 1

Don't store some activations in forward pass

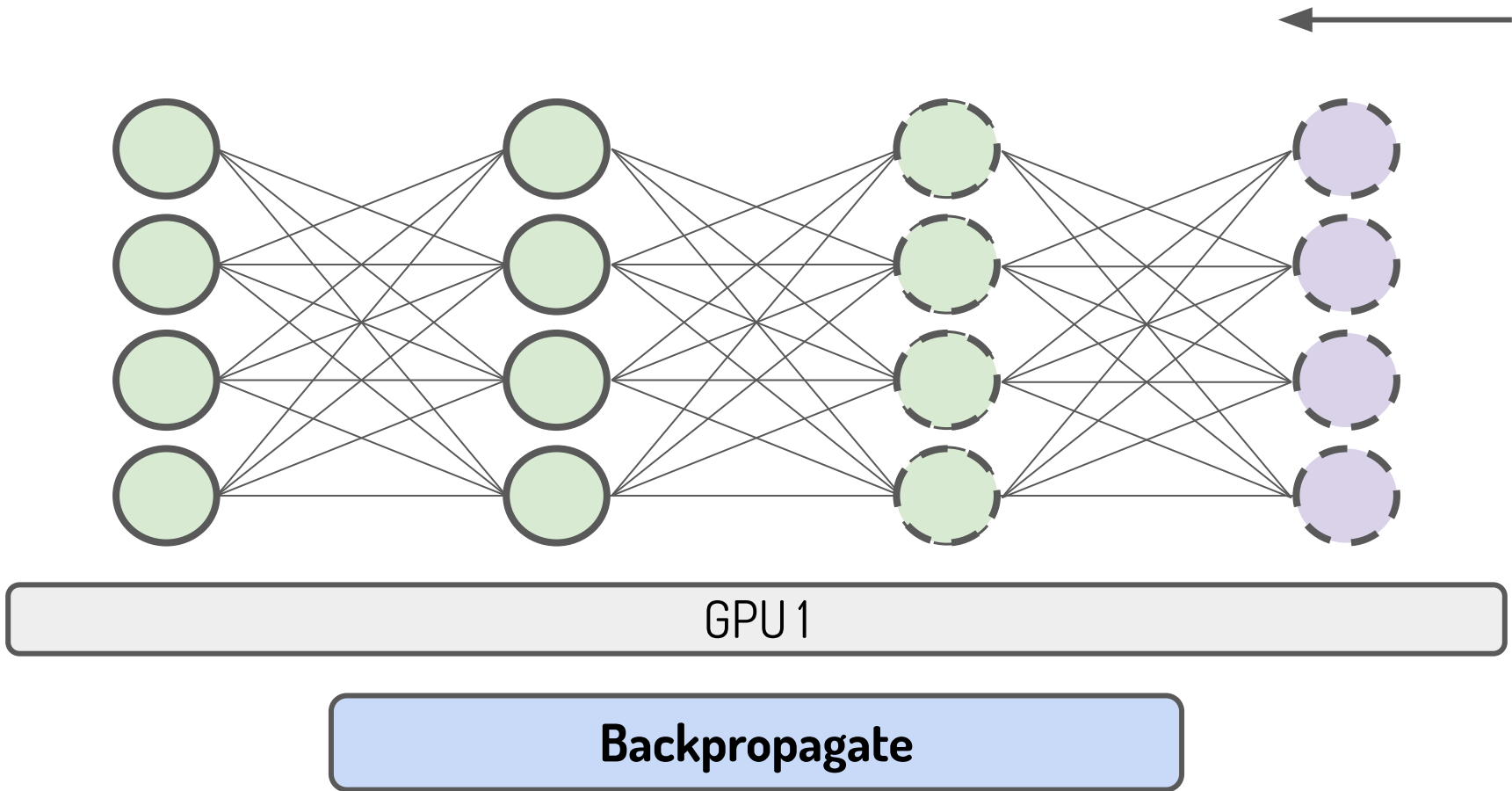


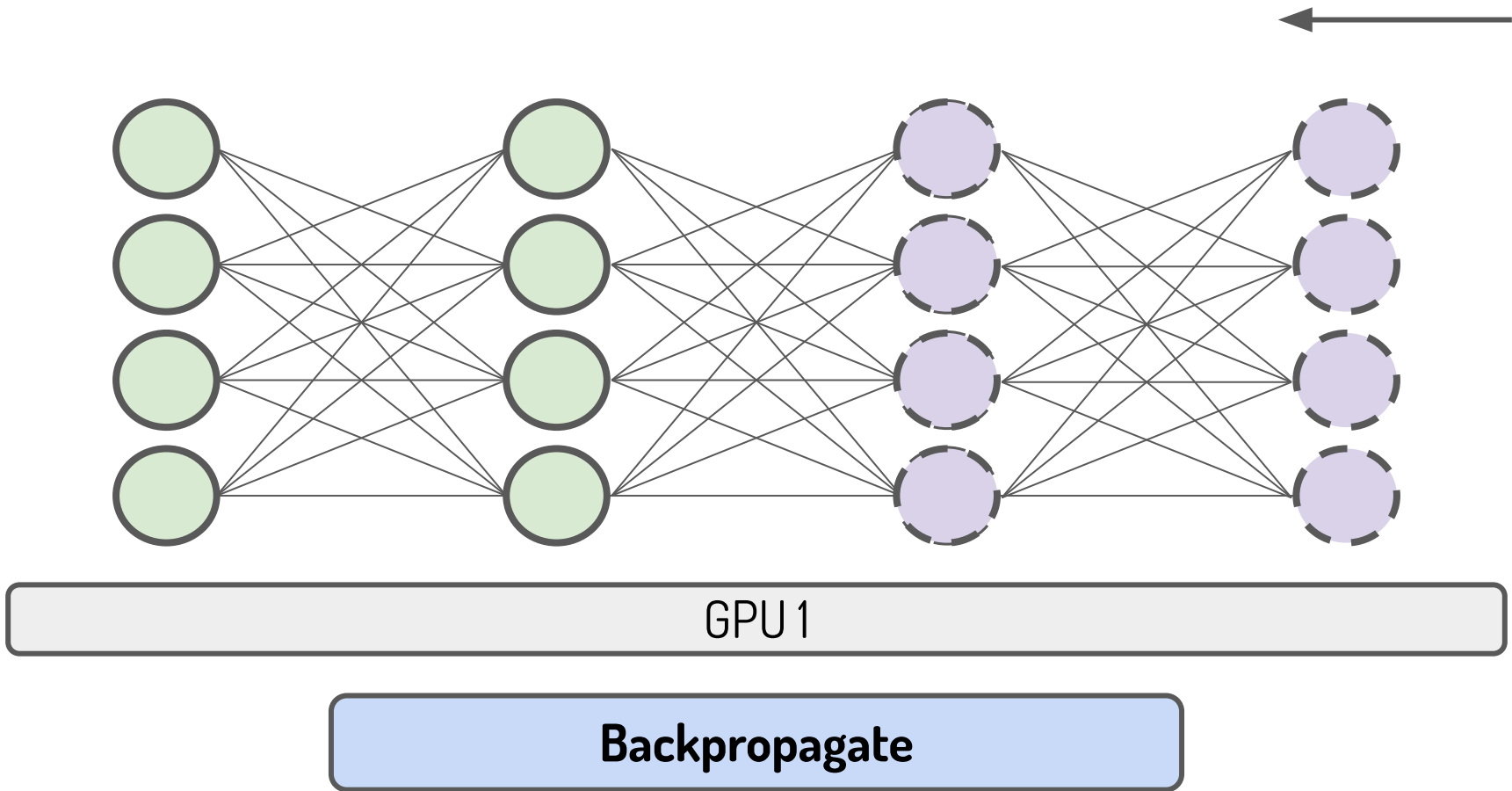


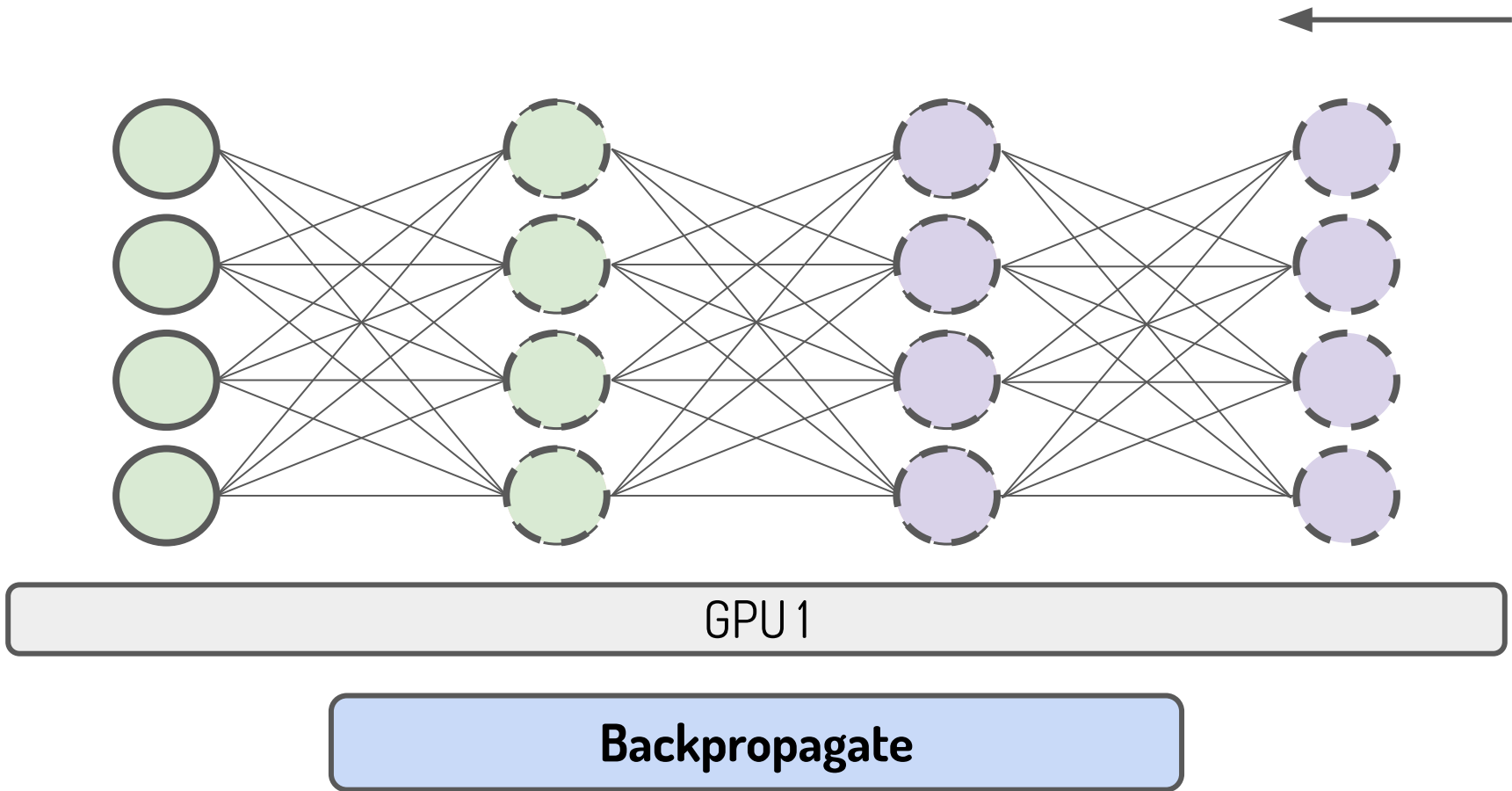
Don't have activations!

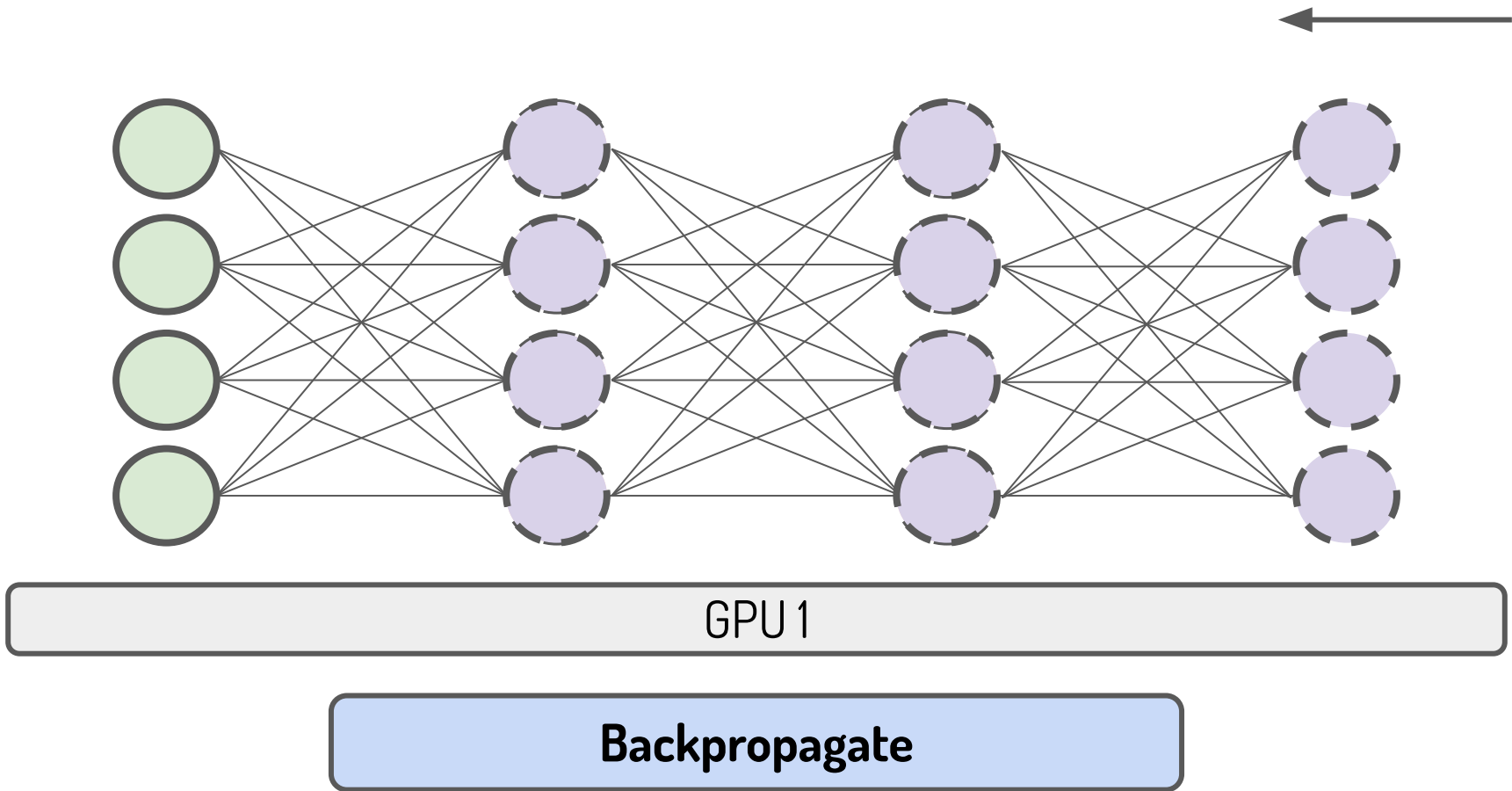


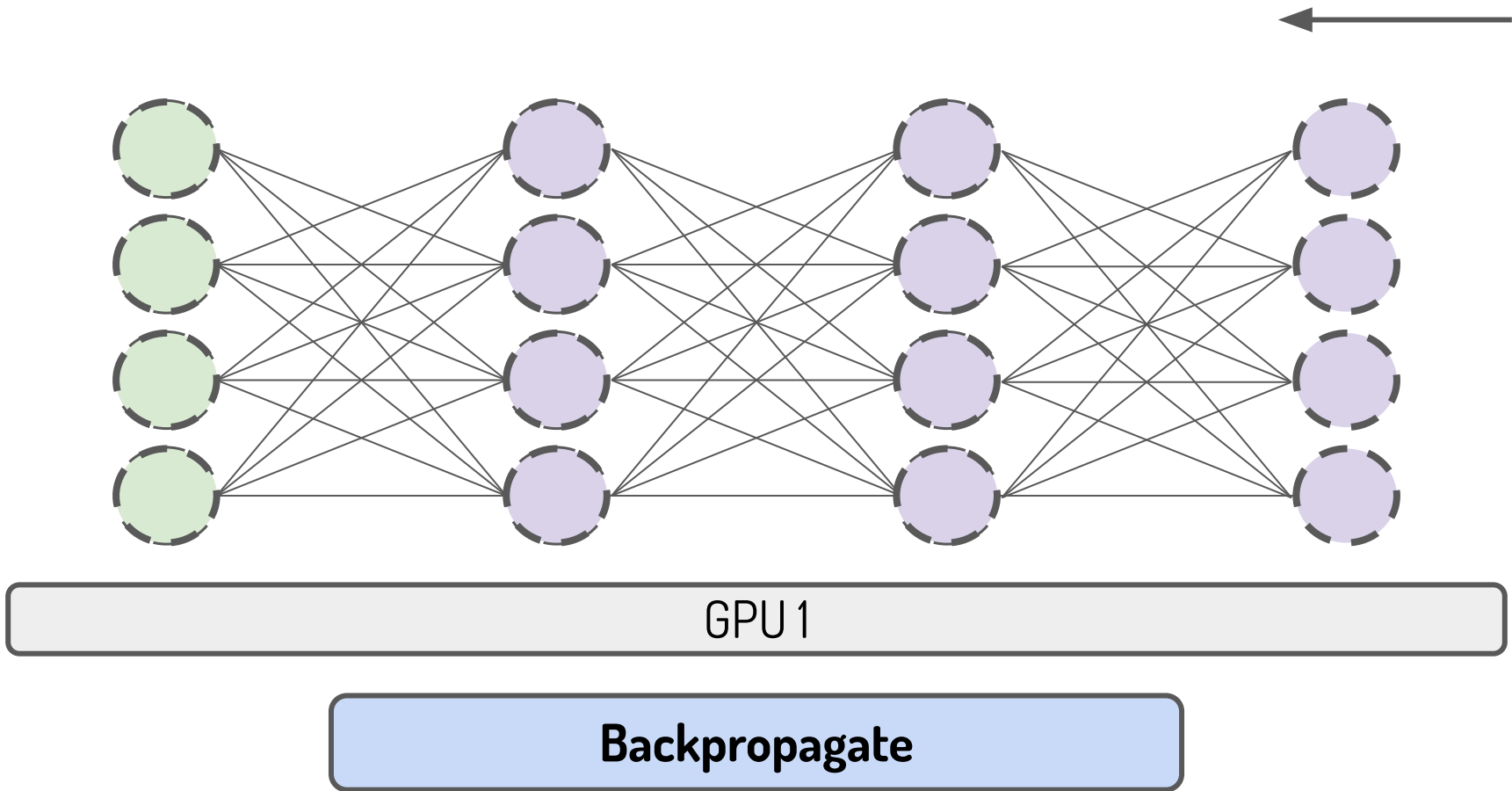
Recompute activations from checkpoint

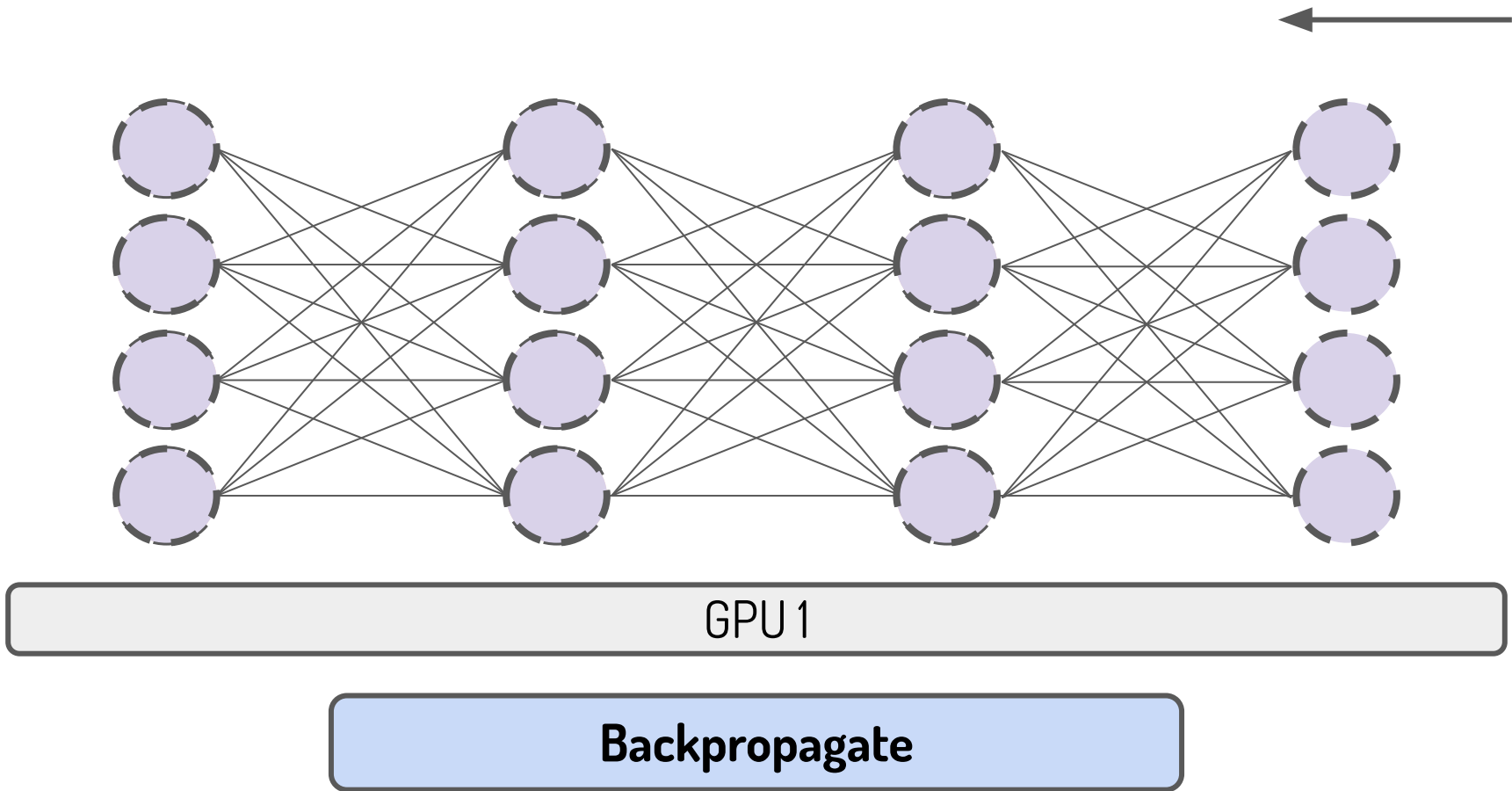












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Modeling Pipeline

Next Lecture: High-Performance Modeling



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